

UJNR 4th Meeting

November 6-8, 2002

at Metropolitan Morioka New Wing, Morioka, Japan

Seismic Risk Management of a Structure Fully Utilizing Recent Seismological Knowledge

Yuji TAKAHASHI:

Building Research Institute, JAPAN

Armen DER KIUREGHIAN: UC Berkeley, USA

Alfredo H-S. ANG:

UC Irvine, USA

Topics

1.

2.

3.

4.

5.



Topics

1. **Seismic risk management**

2.

3.

4.

5.



Topics

1. **Seismic risk management**
2. **Formulation of life-cycle cost**
- 3.
- 4.
- 5.



Topics

1. **Seismic risk management**
2. **Formulation of life-cycle cost**
3. **Application to a building in Tokyo**
- 4.
- 5.



Topics

1. **Seismic risk management**
2. **Formulation of life-cycle cost**
3. **Application to a building in Tokyo**
4. **Conclusions**
- 5.

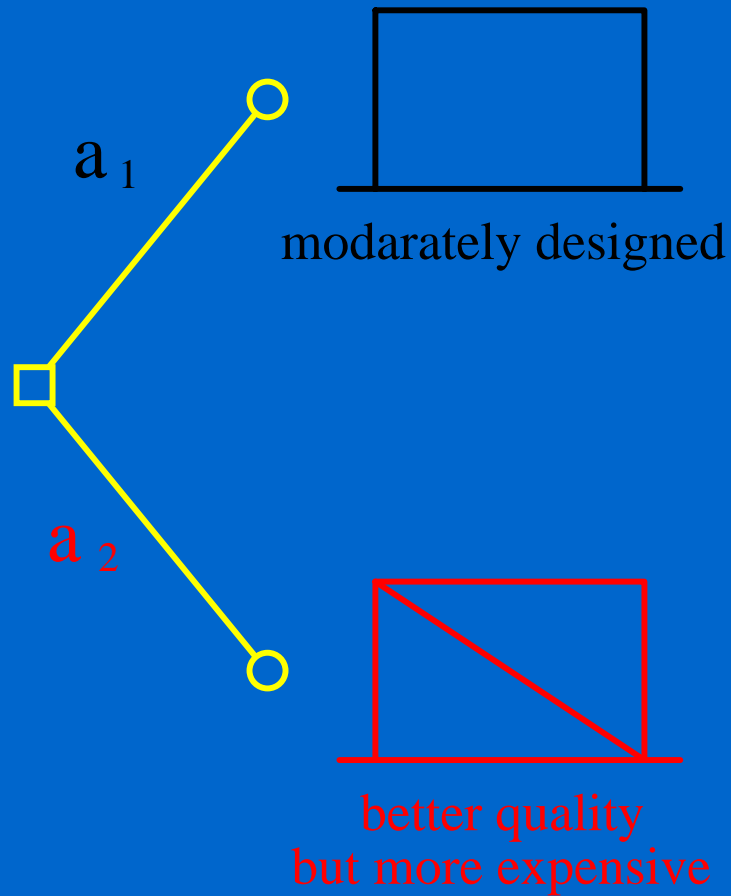


Topics

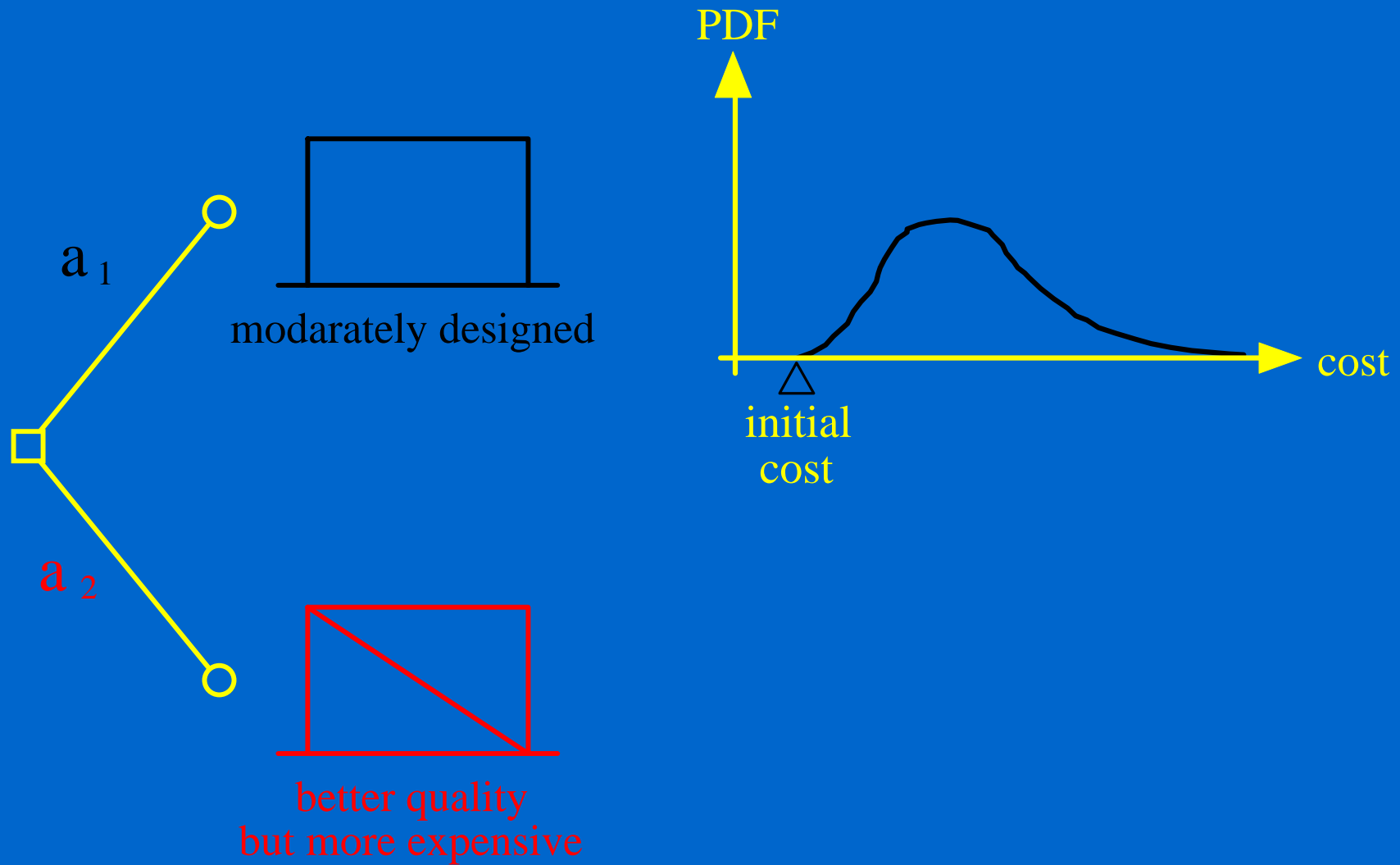
1. **Seismic risk management**
2. **Formulation of life-cycle cost**
3. **Application to a building in Tokyo**
4. **Conclusions**
5. **Current study**



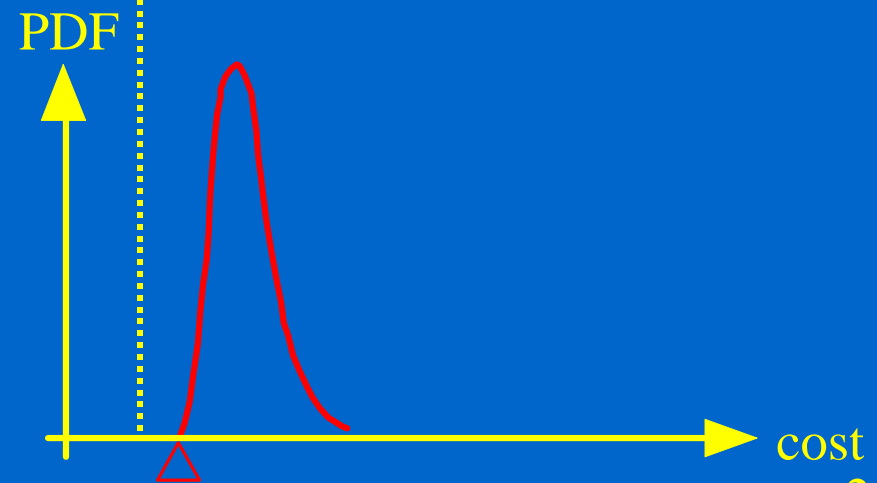
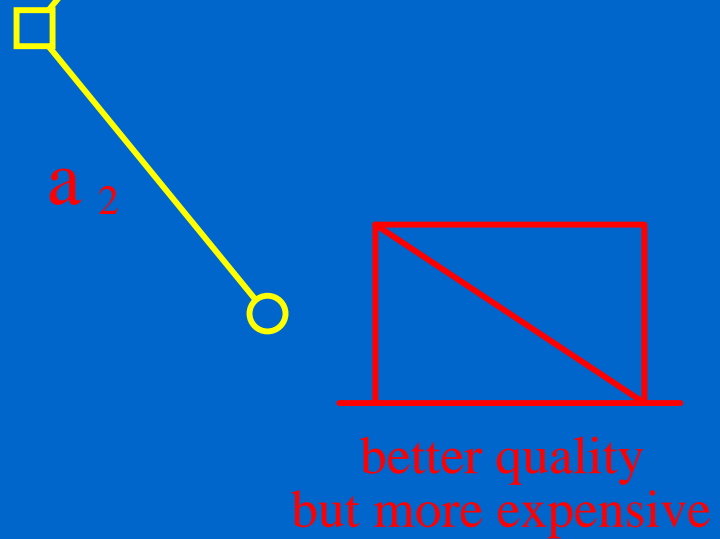
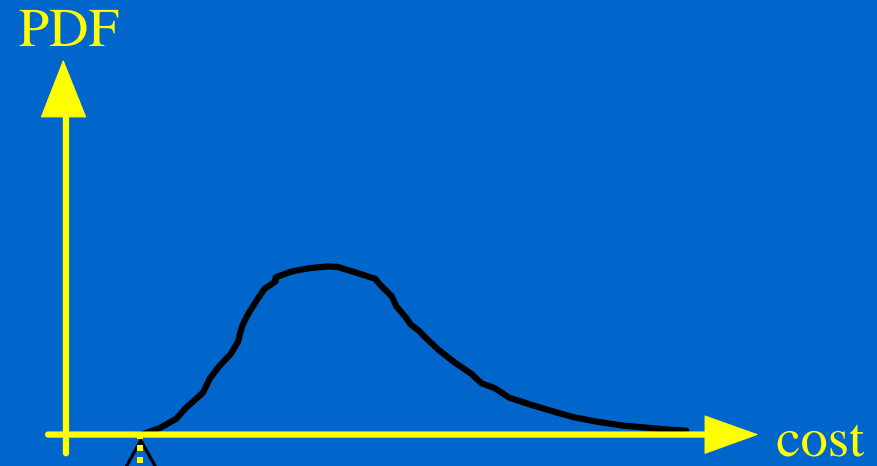
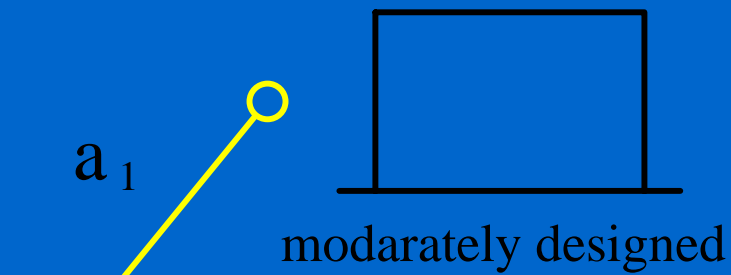
Seismic risk management



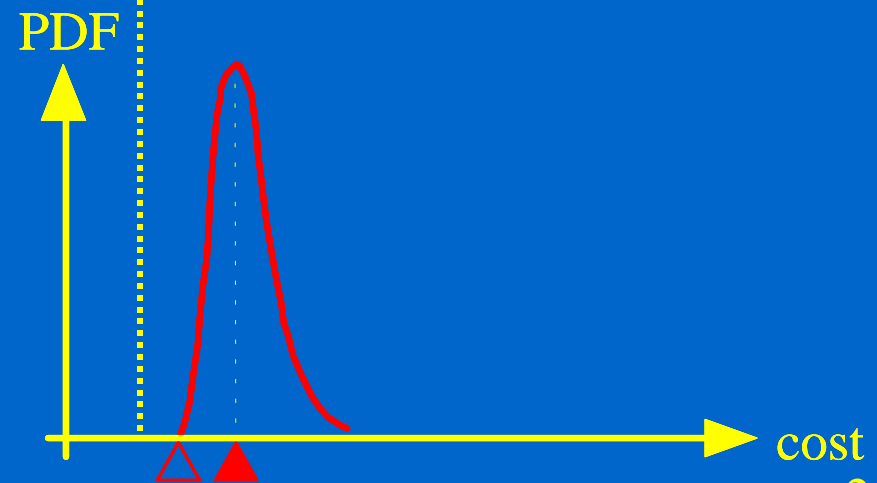
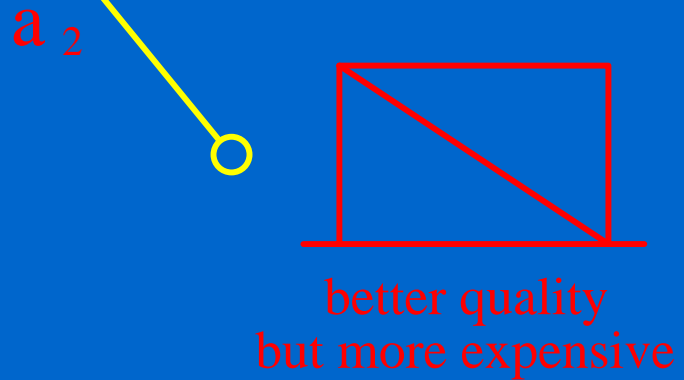
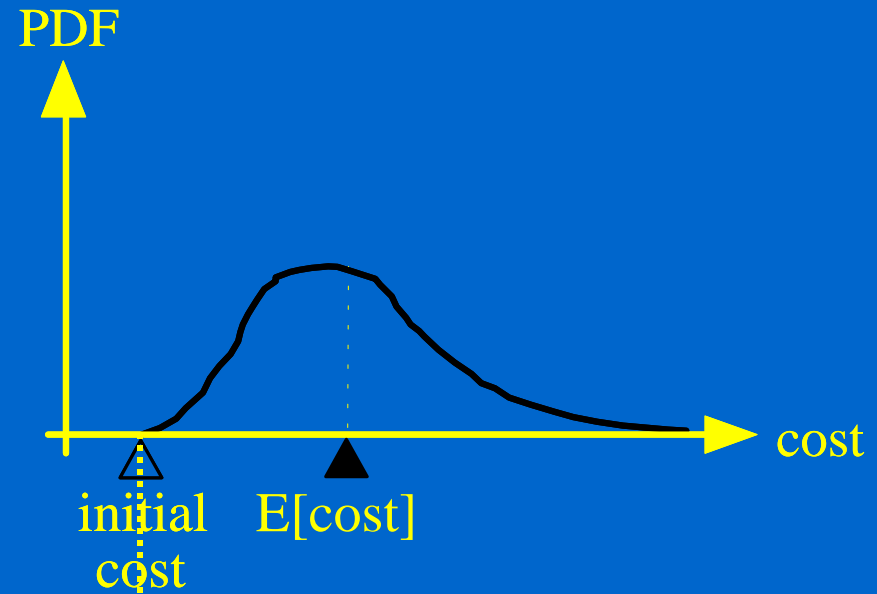
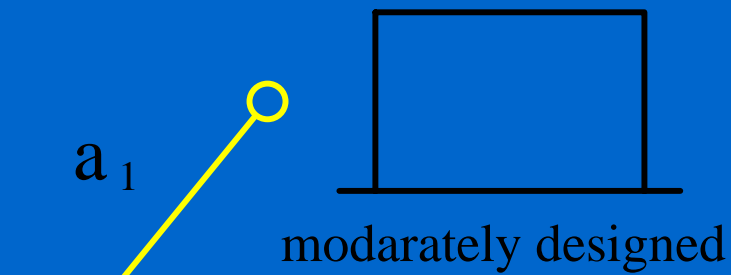
Seismic risk management



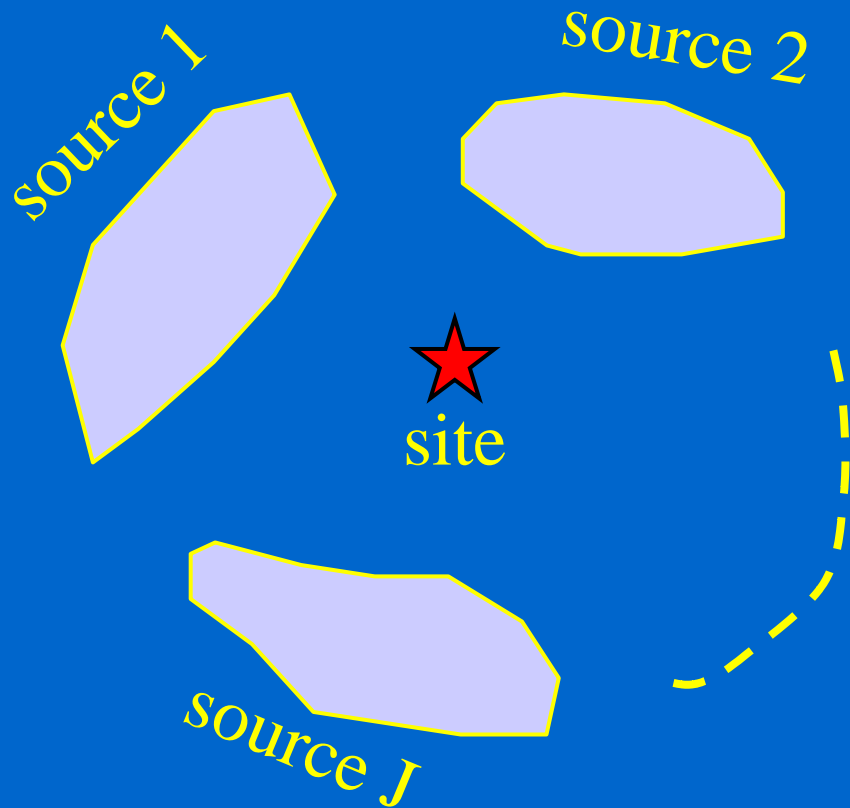
Seismic risk management



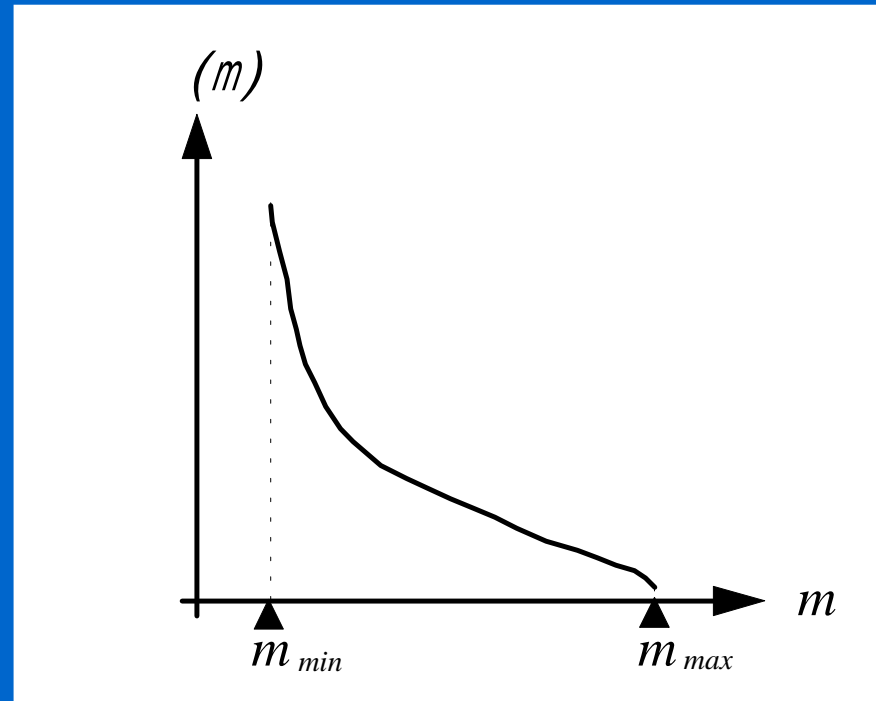
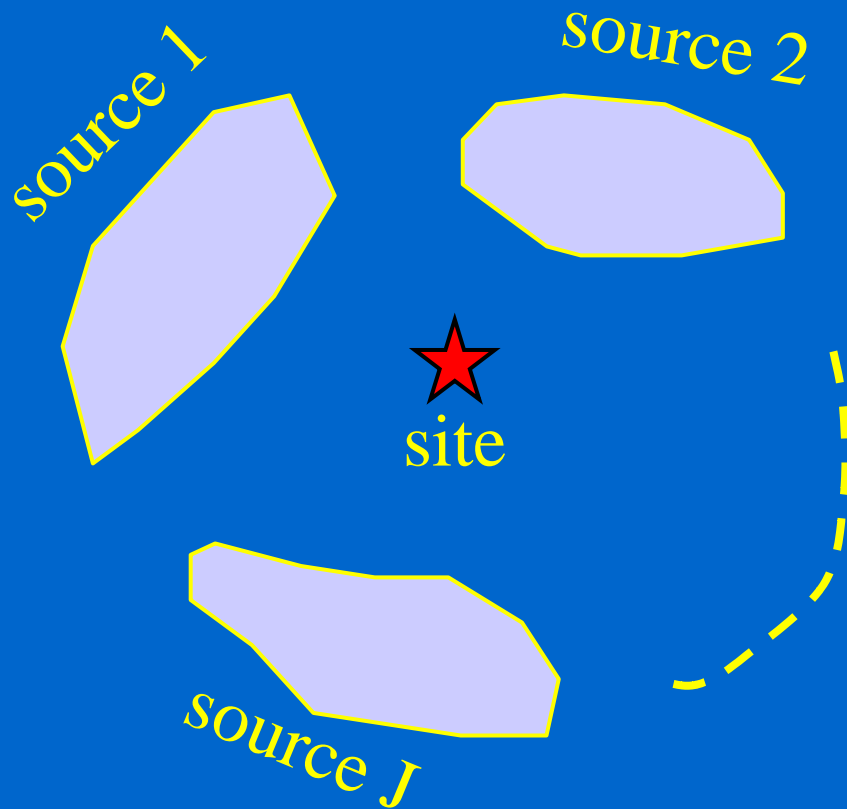
Seismic risk management



Formulation of expected life-cycle cost



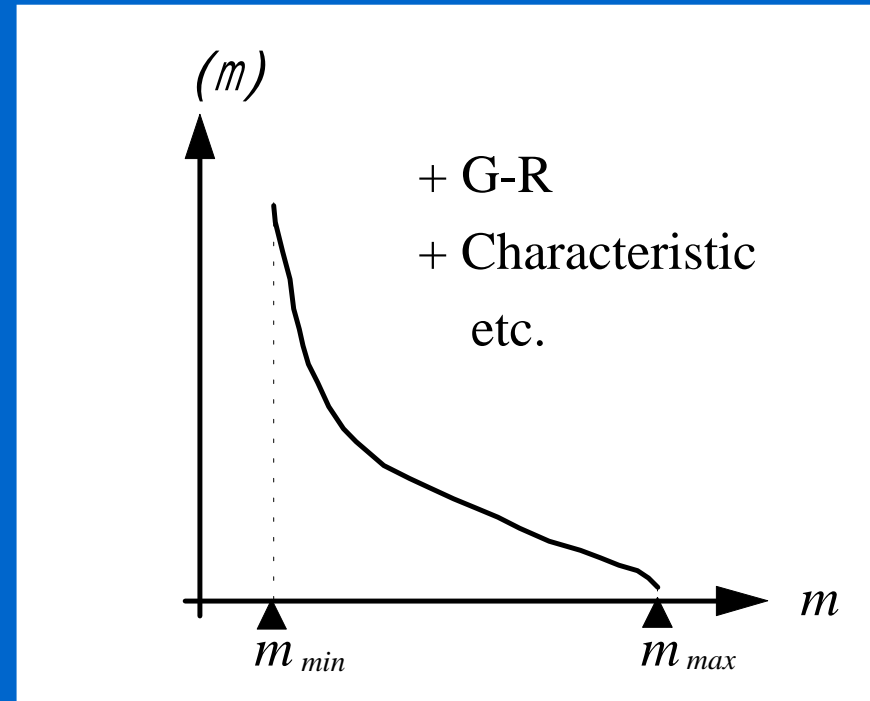
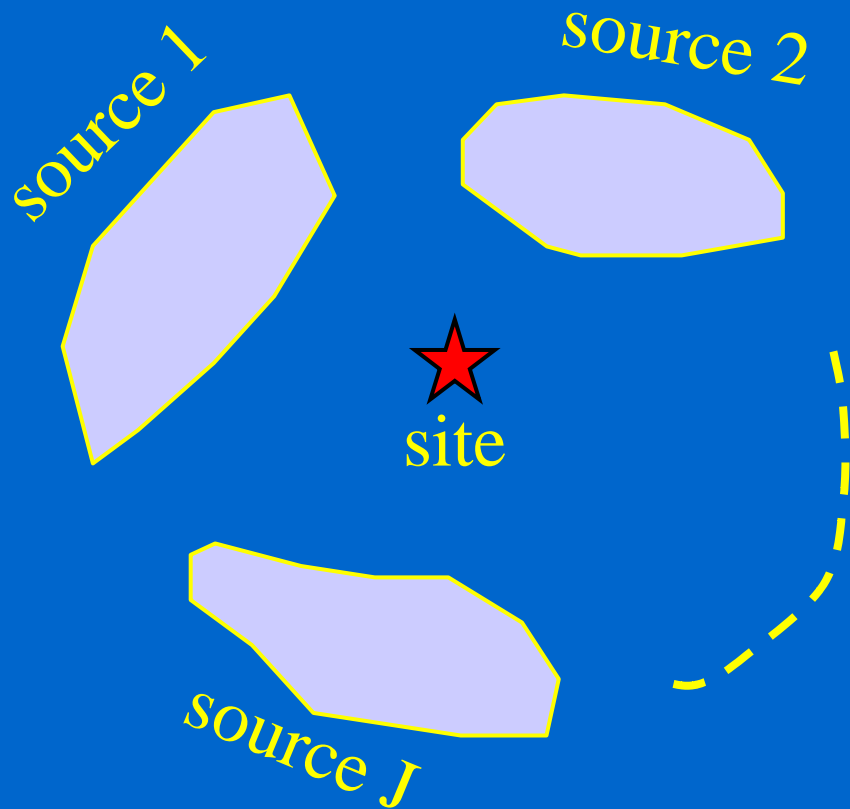
Formulation of expected life-cycle cost



magnitude – annual rate



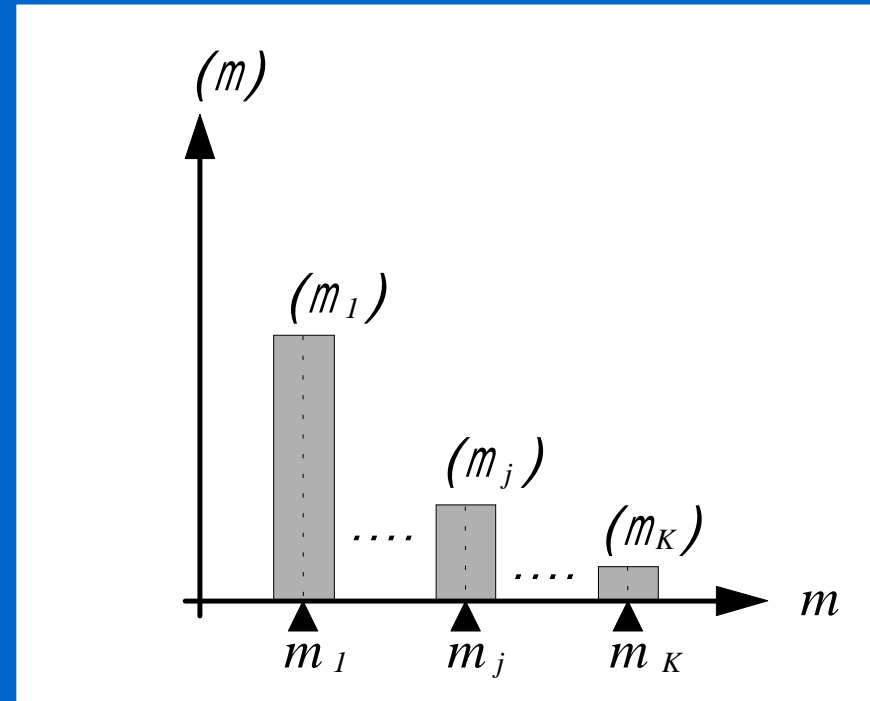
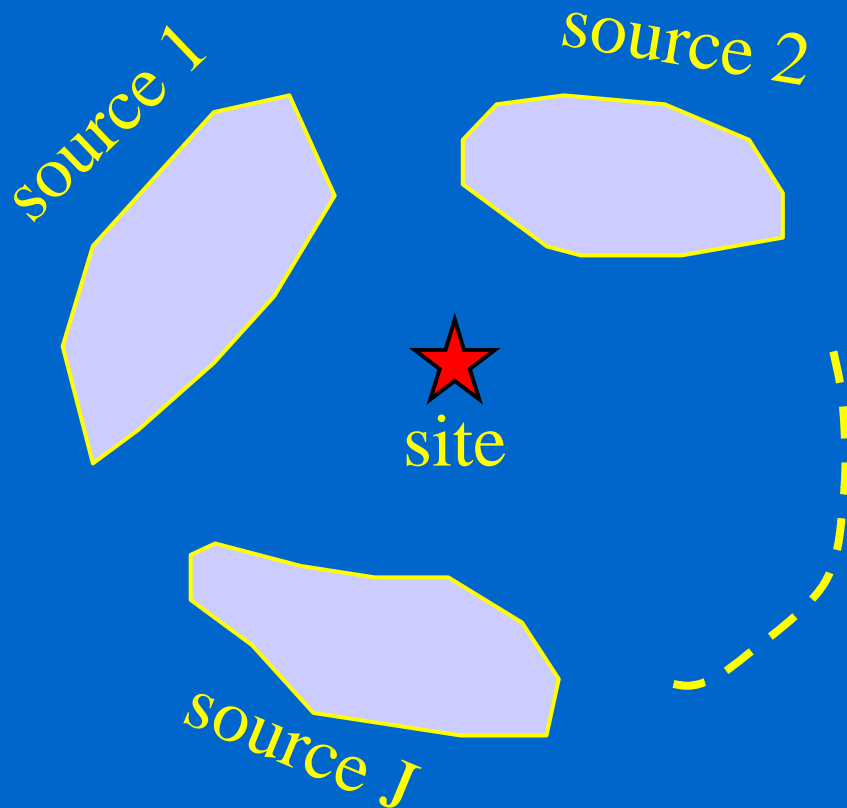
Formulation of expected life-cycle cost



magnitude – annual rate



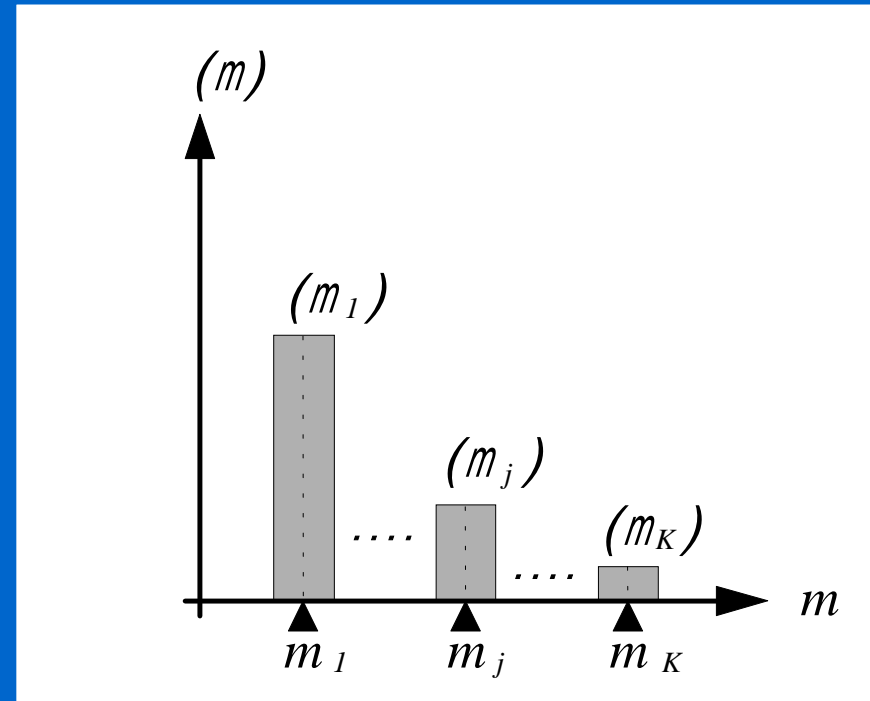
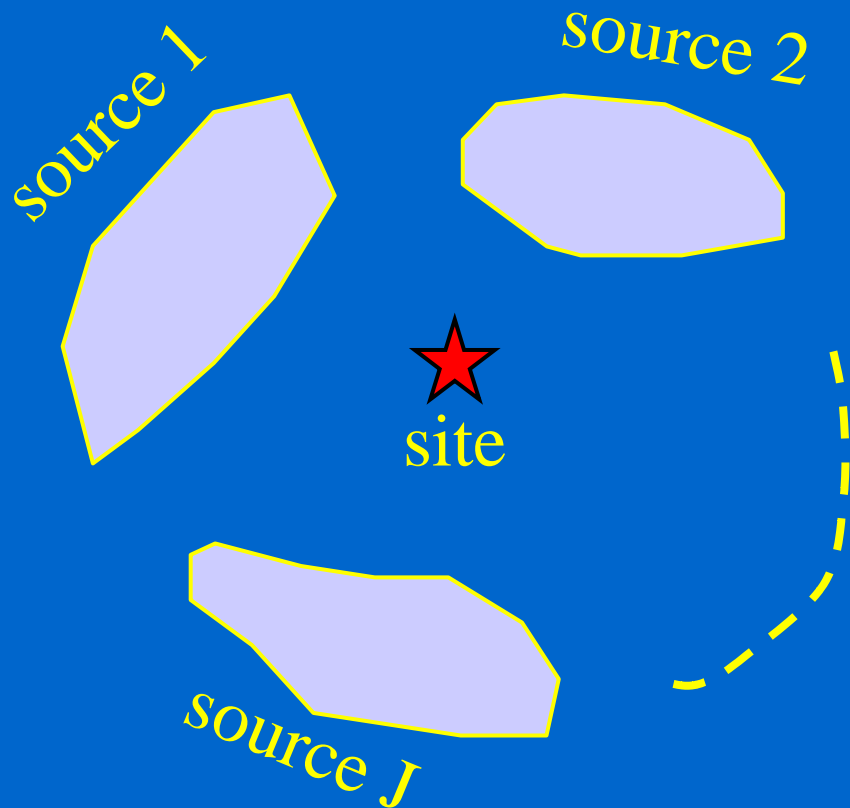
Formulation of expected life-cycle cost



magnitude – annual rate



Formulation of expected life-cycle cost



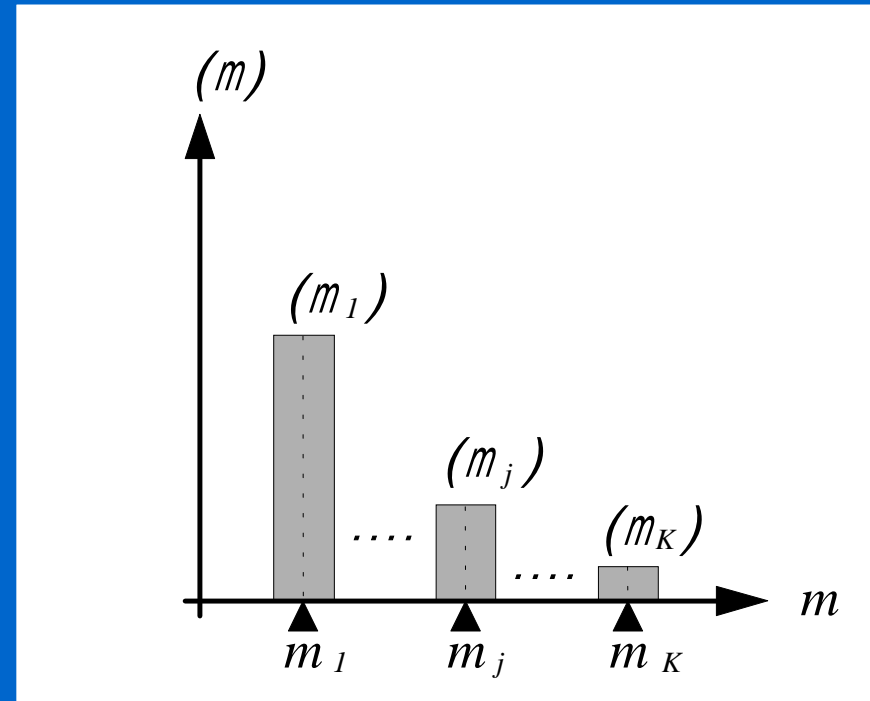
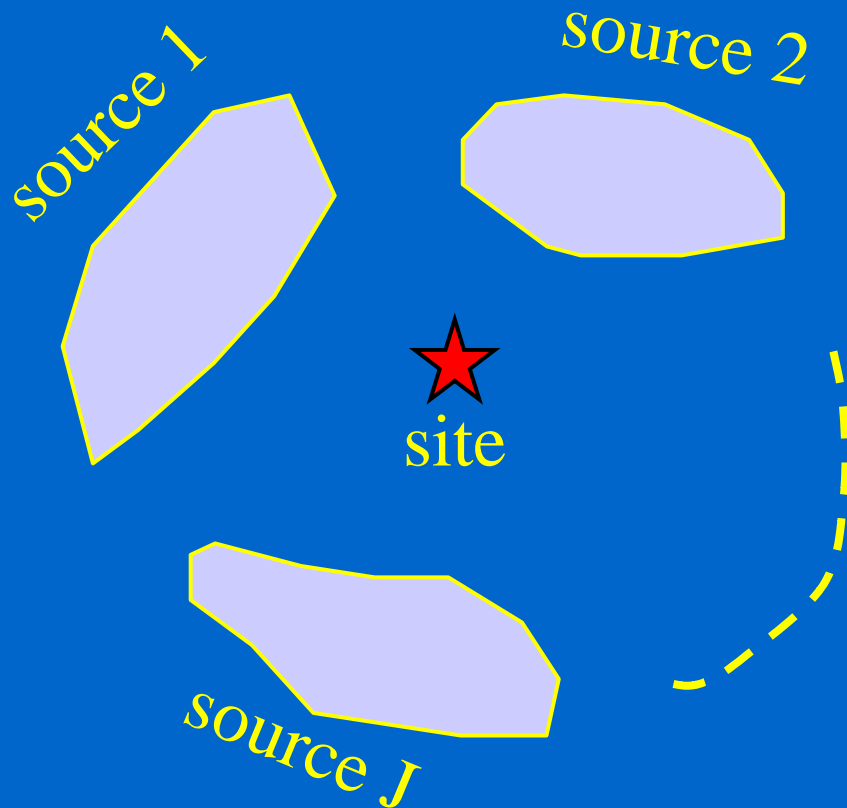
magnitude – annual rate

$$E[C_L] =$$

$$E[C_D(m_j)]$$



Formulation of expected life-cycle cost



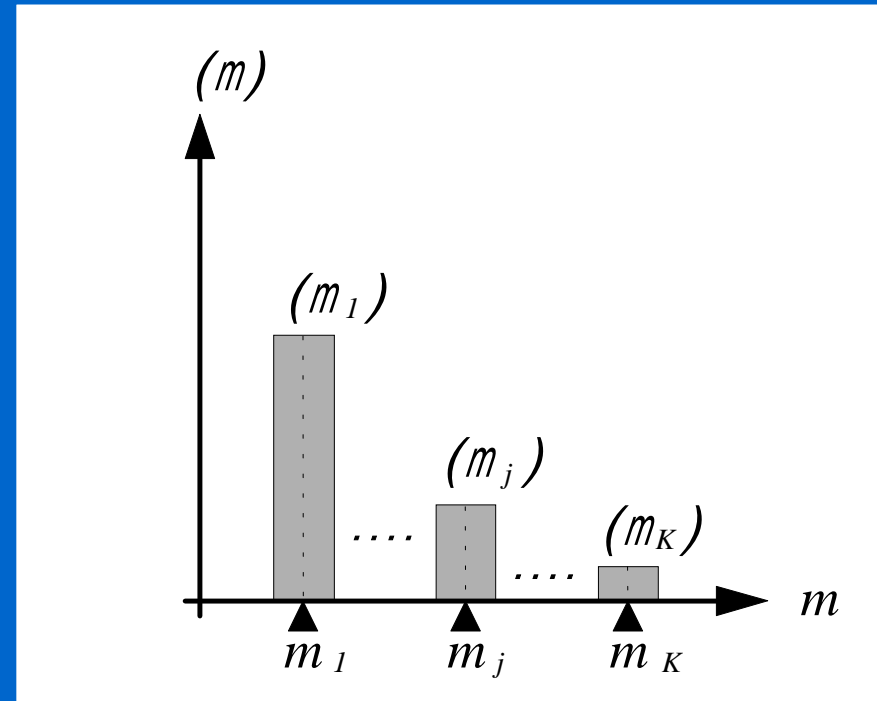
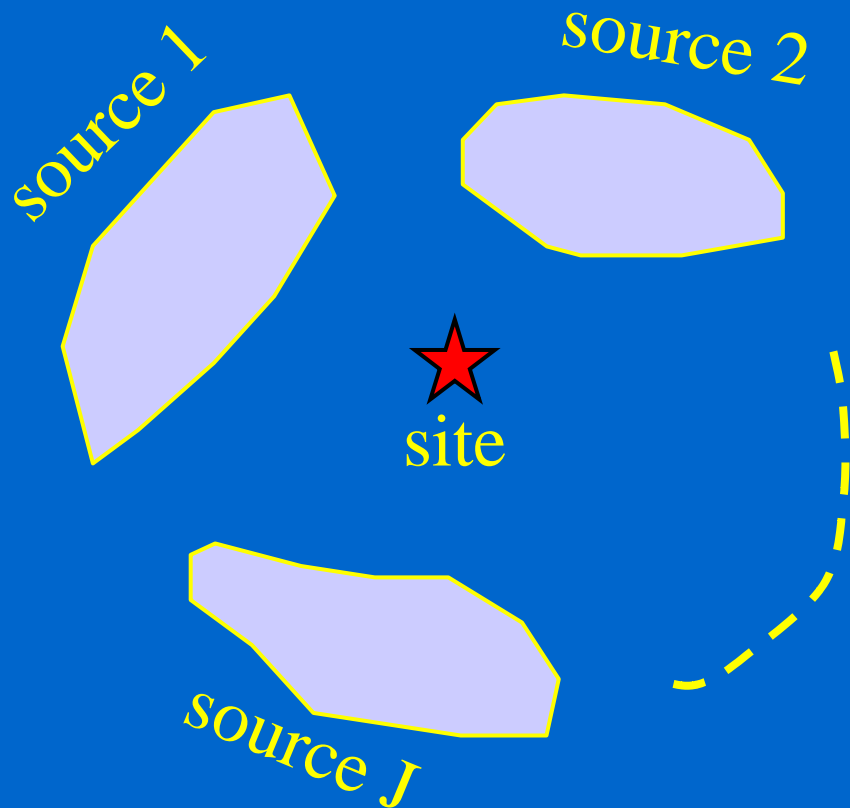
magnitude – annual rate

$$E[C_L] =$$

$$v(m_j) \cdot E[C_D(m_j)]$$



Formulation of expected life-cycle cost



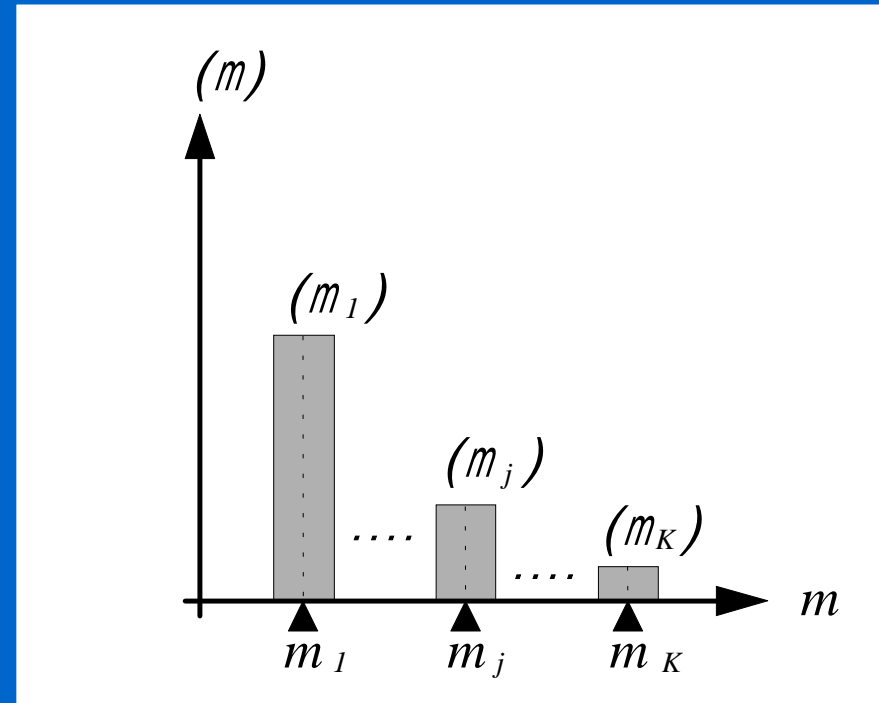
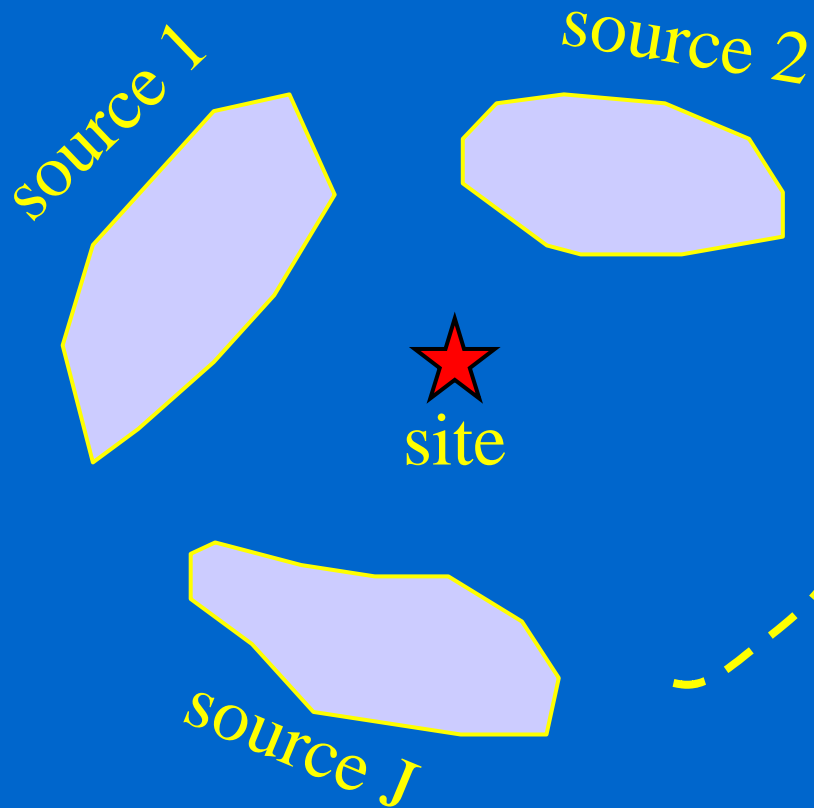
magnitude – annual rate

$$E[C_L] =$$

$$\sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



Formulation of expected life-cycle cost

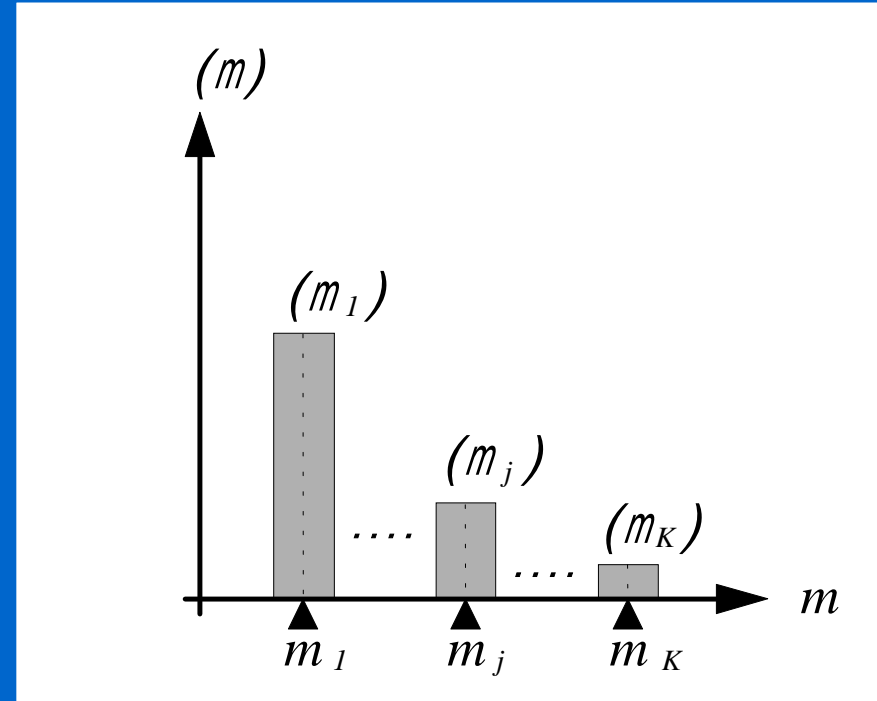
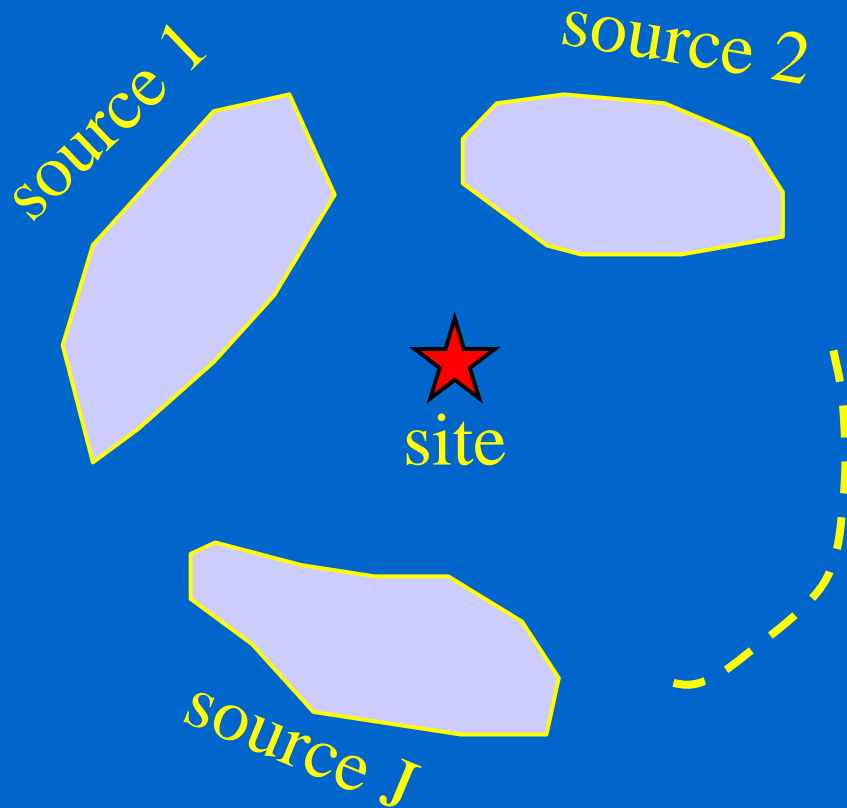


magnitude – annual rate

$$E[C_L] = \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



Formulation of expected life-cycle cost

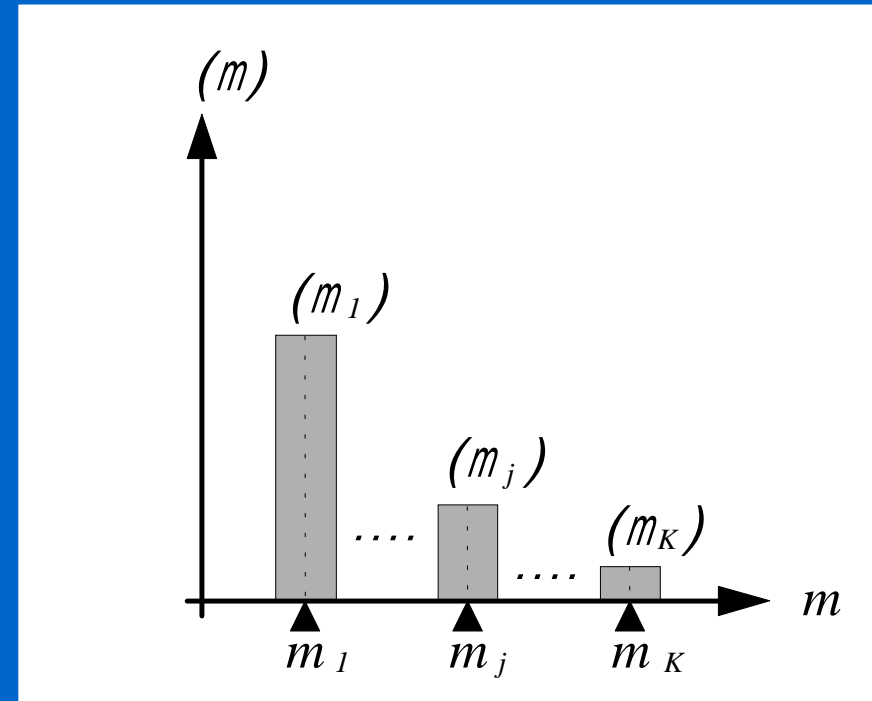
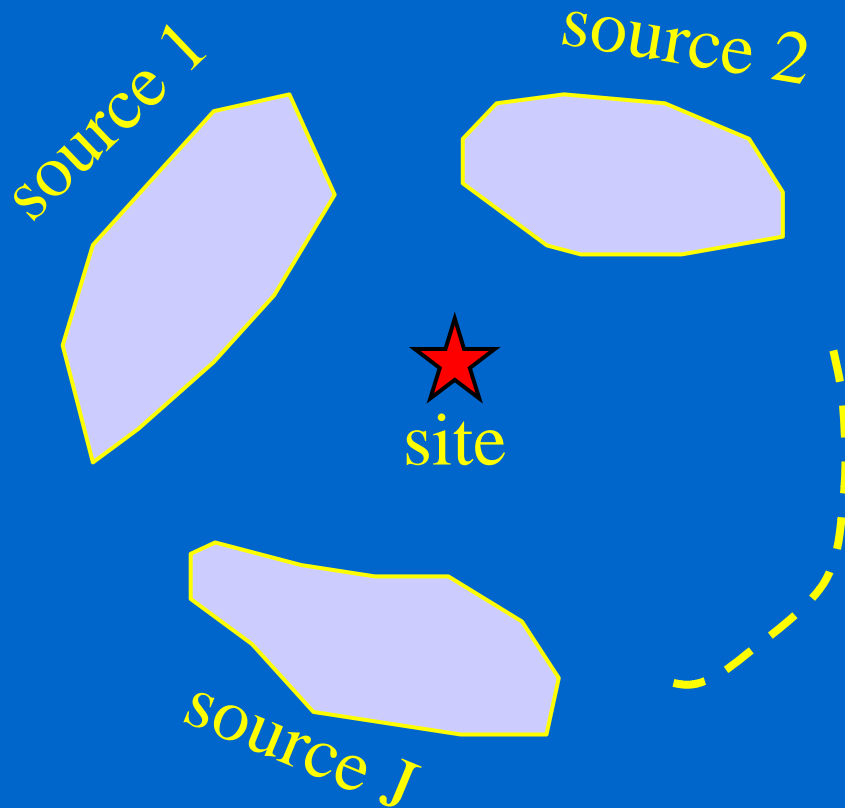


magnitude – annual rate

$$E[C_L] = \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



Formulation of expected life-cycle cost



magnitude – annual rate

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



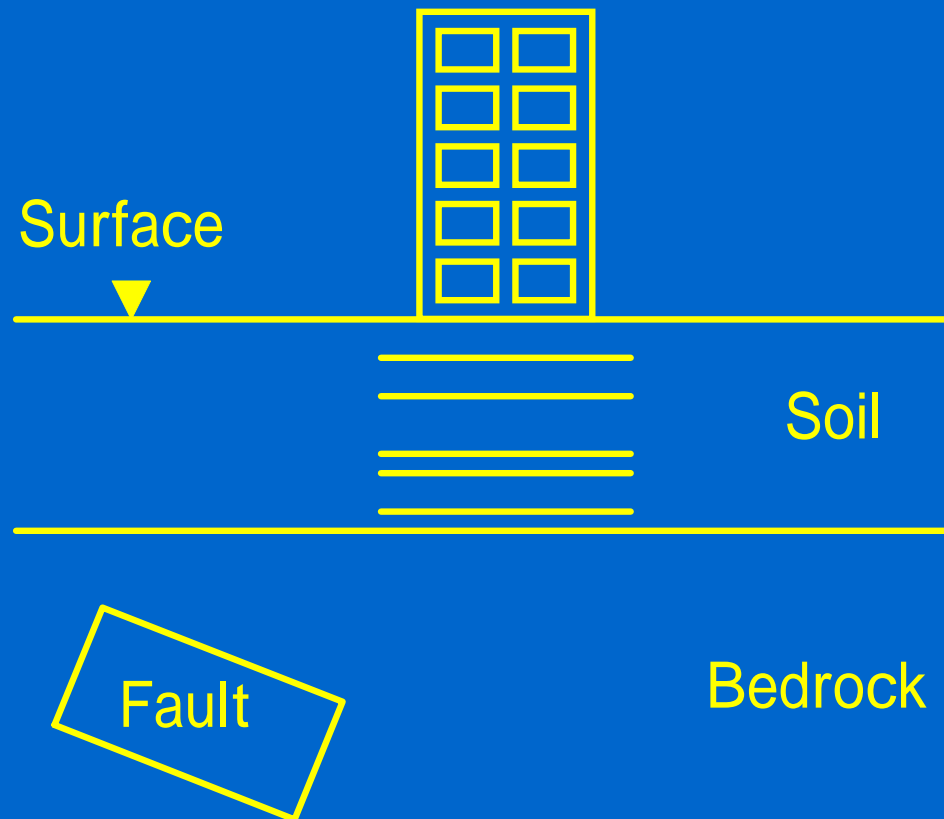
Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] \quad ?$$



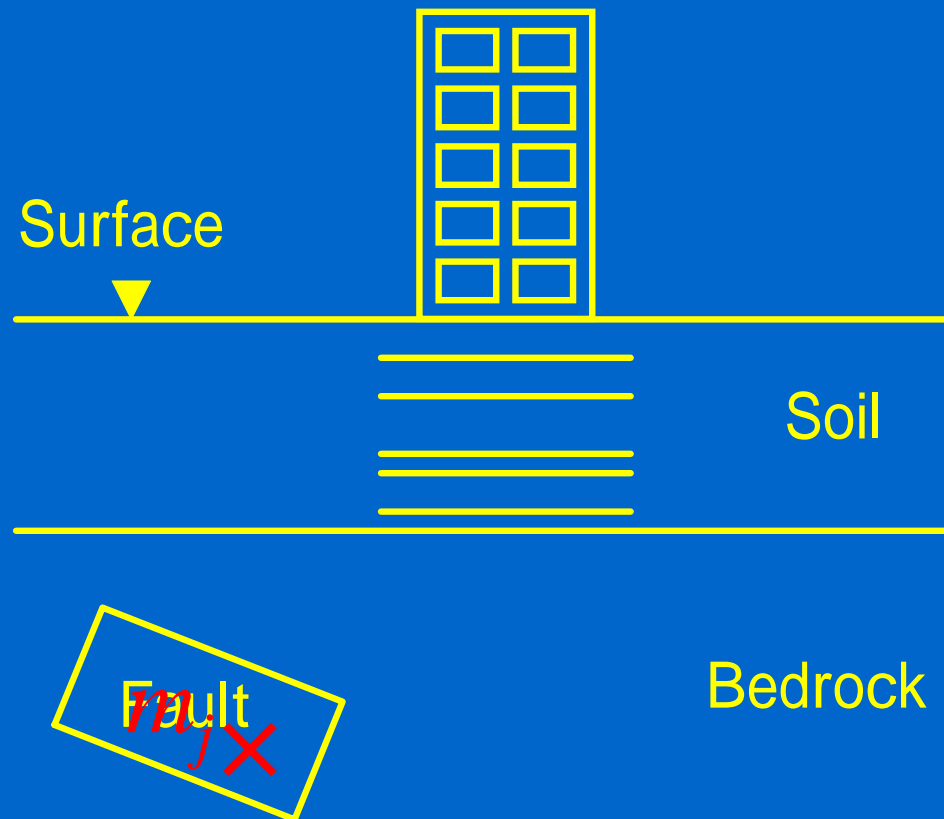
Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] ?$$



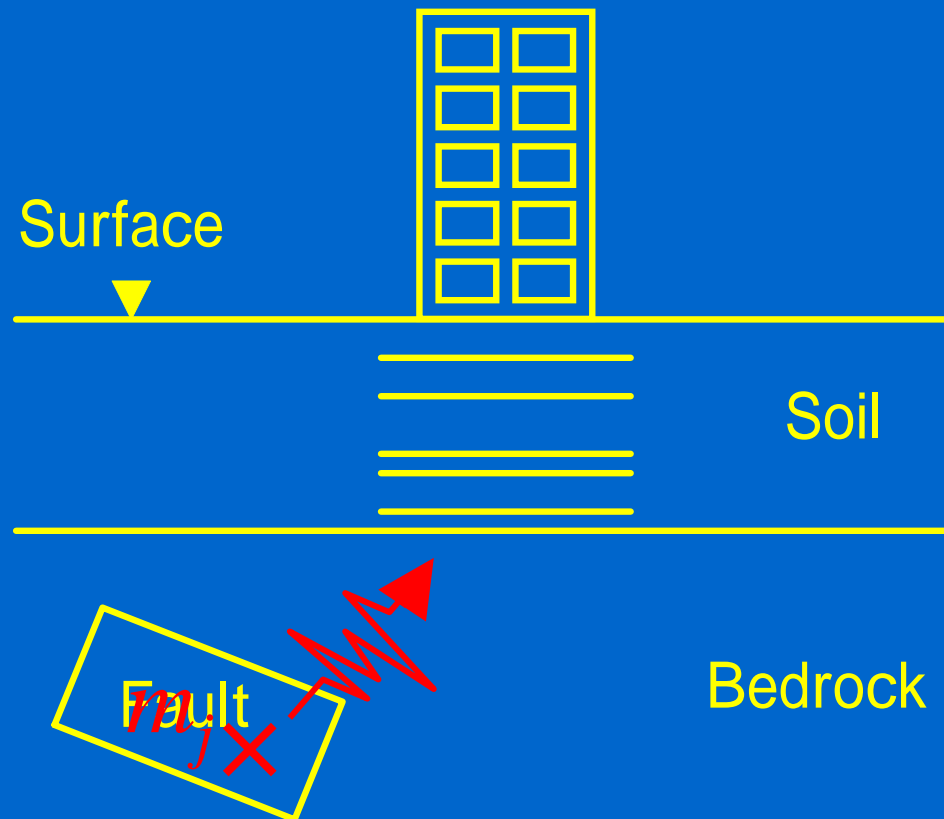
Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] ?$$



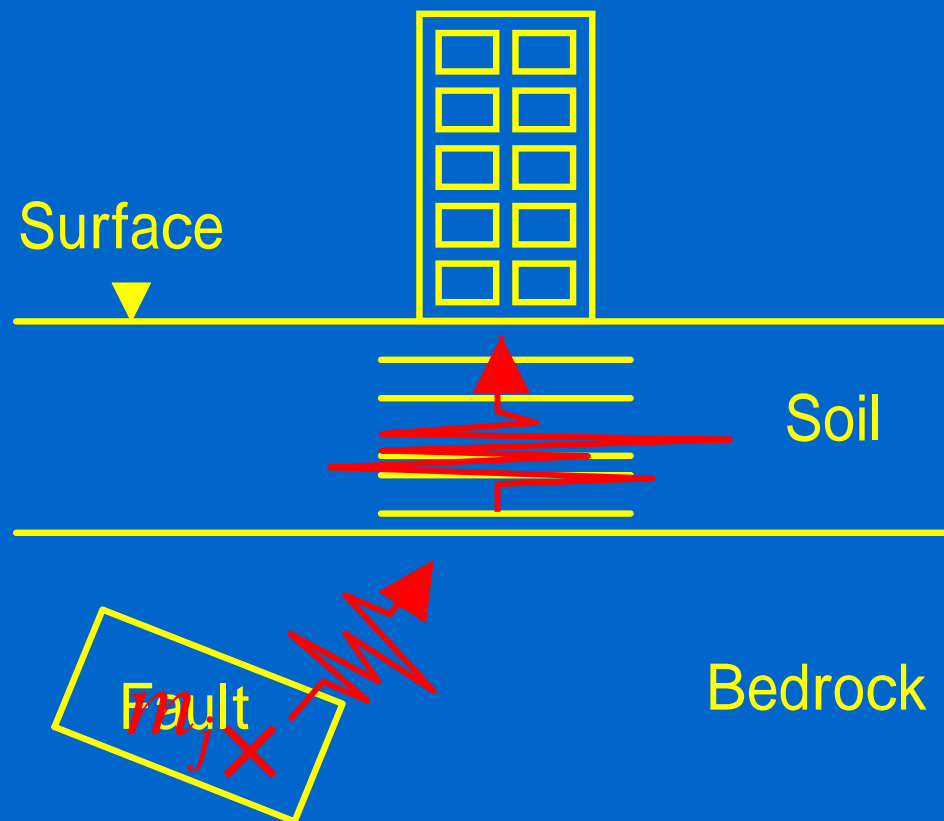
Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] ?$$



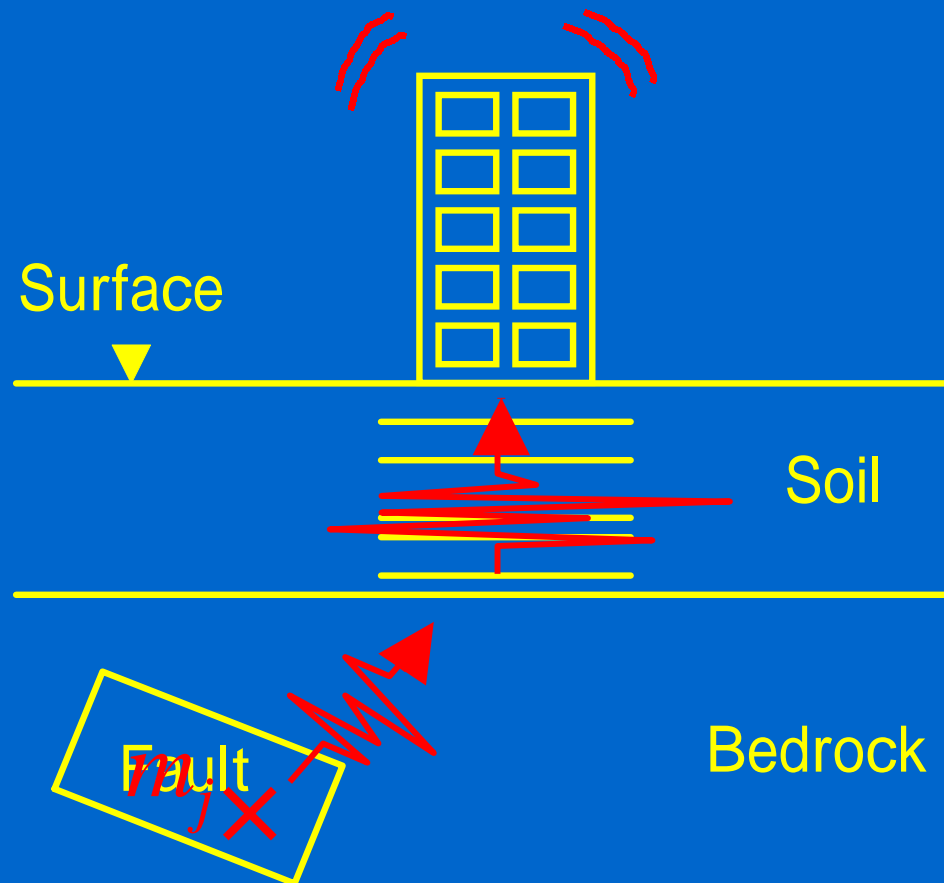
Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] ?$$



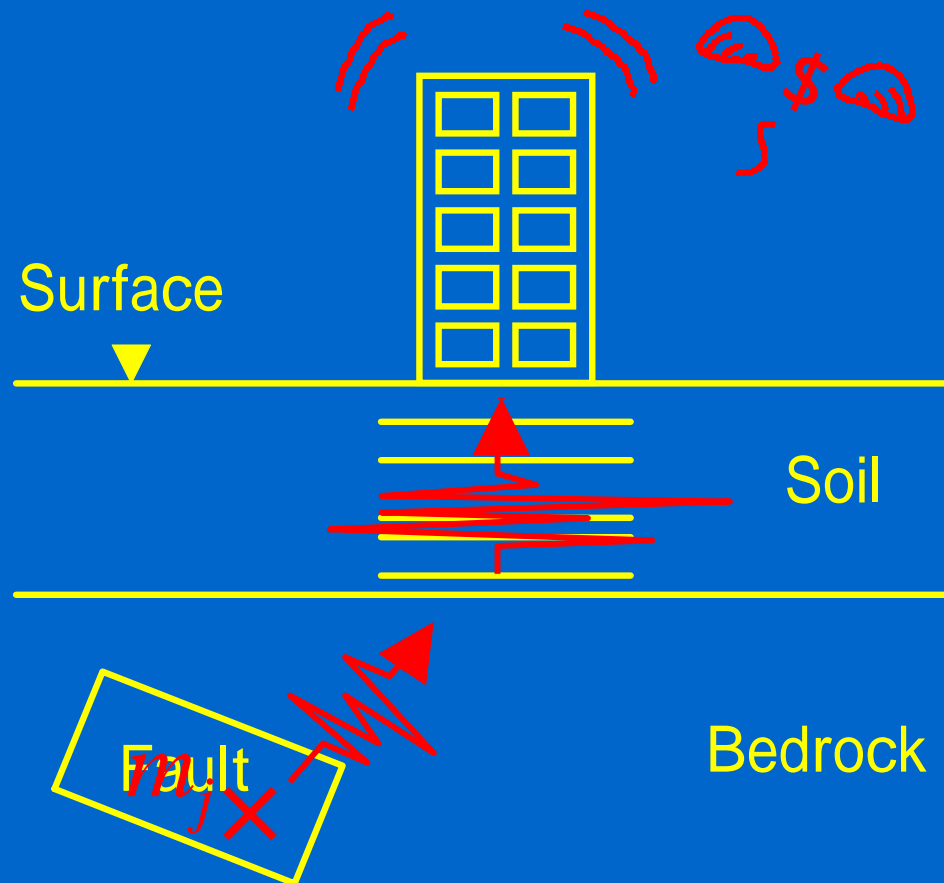
Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] ?$$



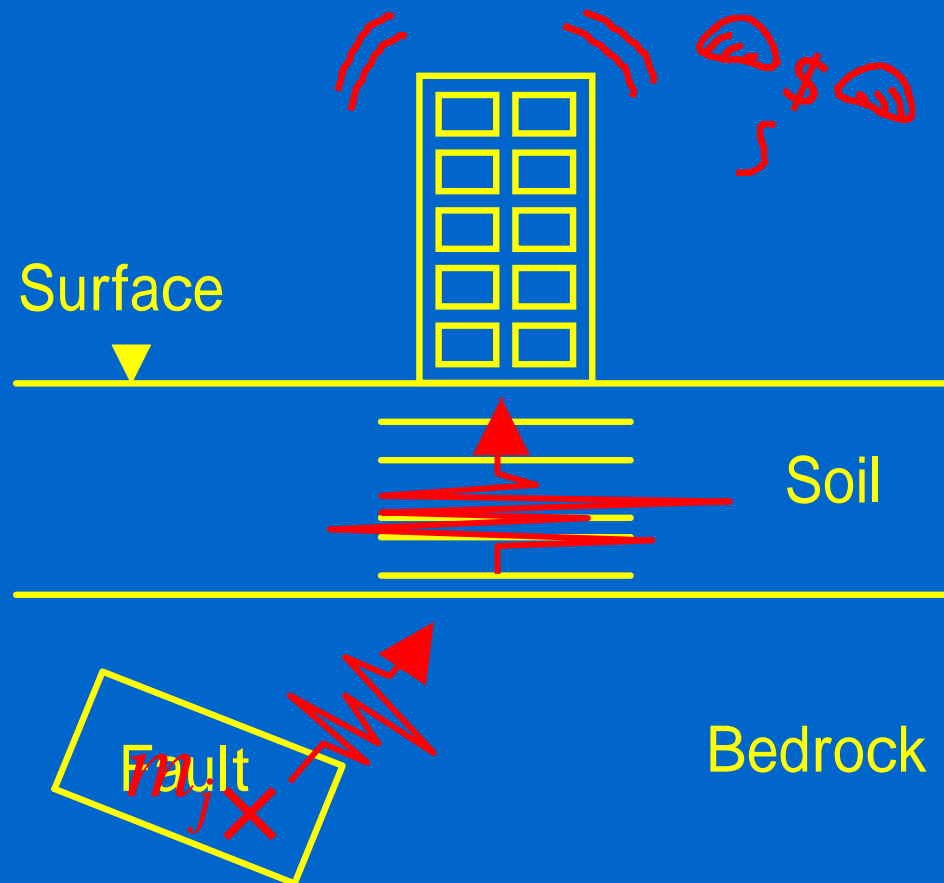
Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] ?$$



Expected damage cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)] ?$$



Monte Carlo simulation !



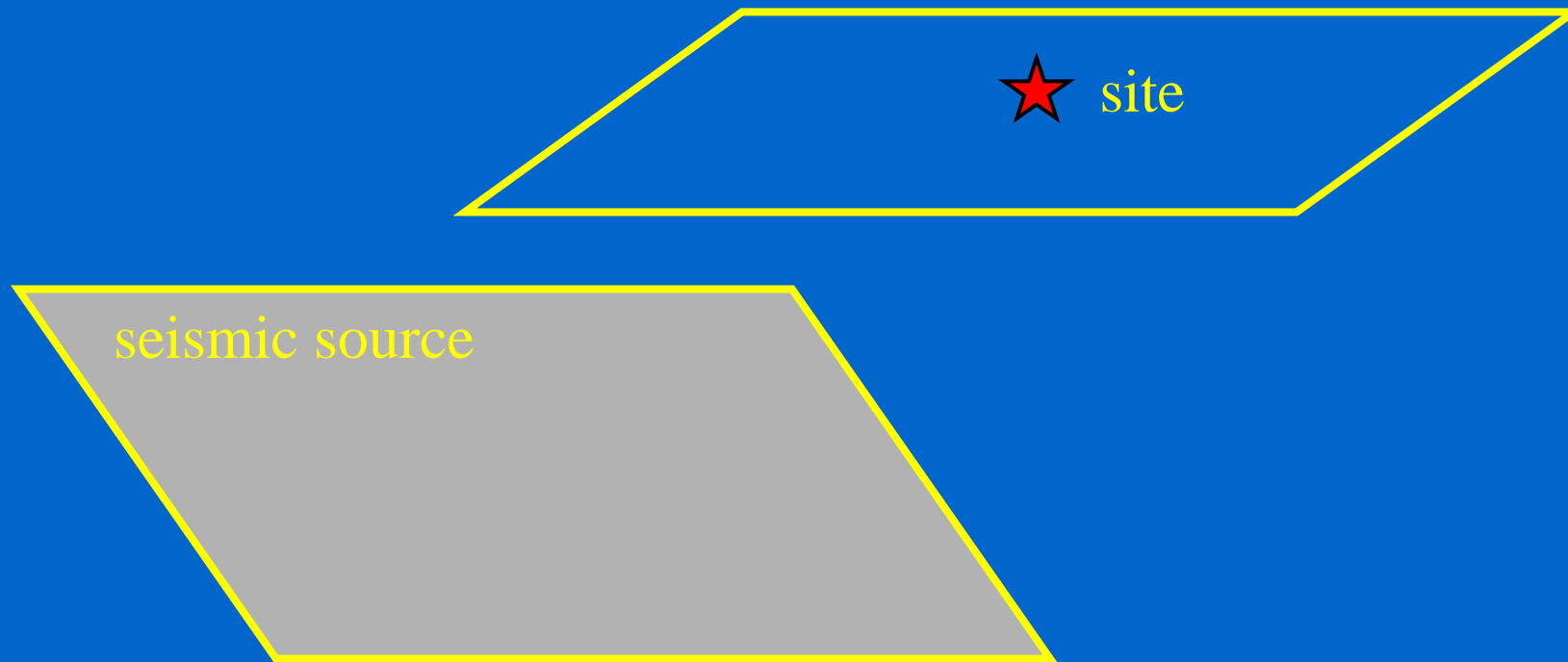
Seismological model

Finite-fault stochastic Green's function method



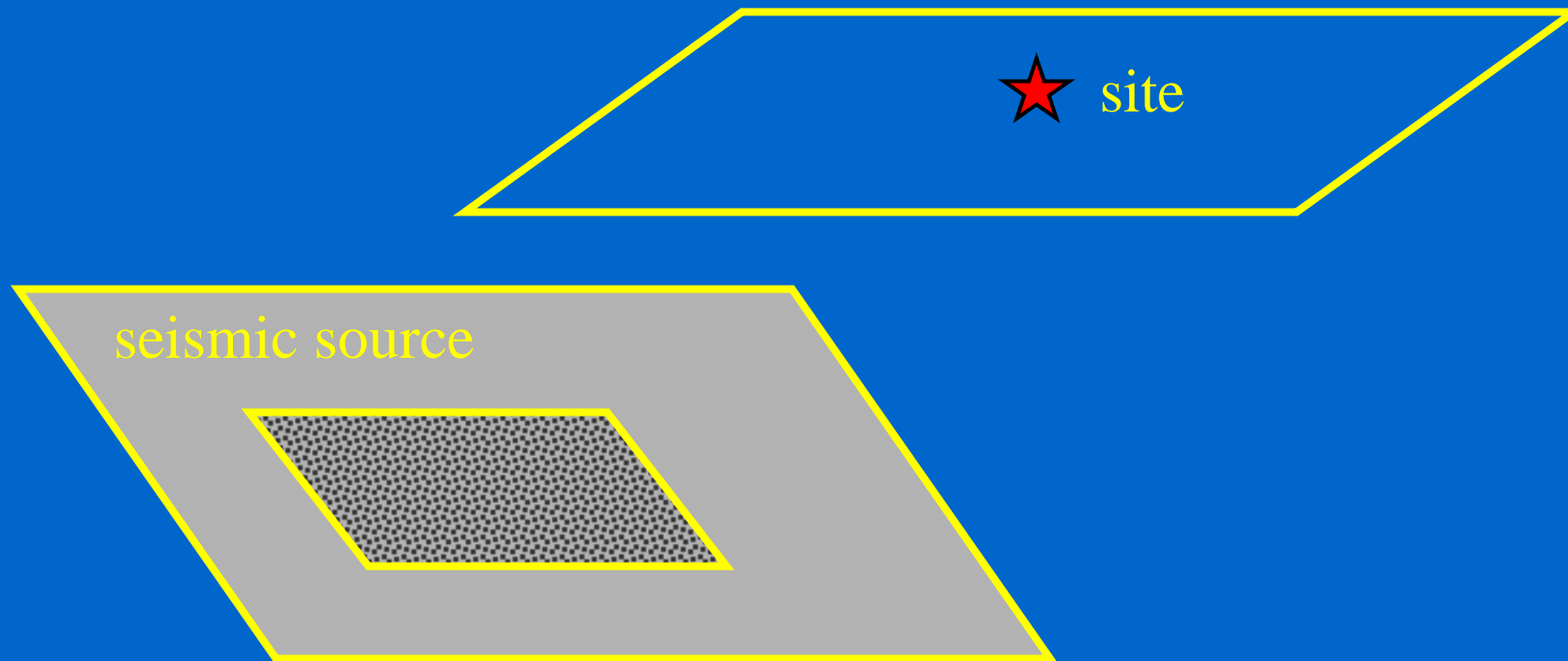
Seismological model

Finite-fault stochastic Green's function method



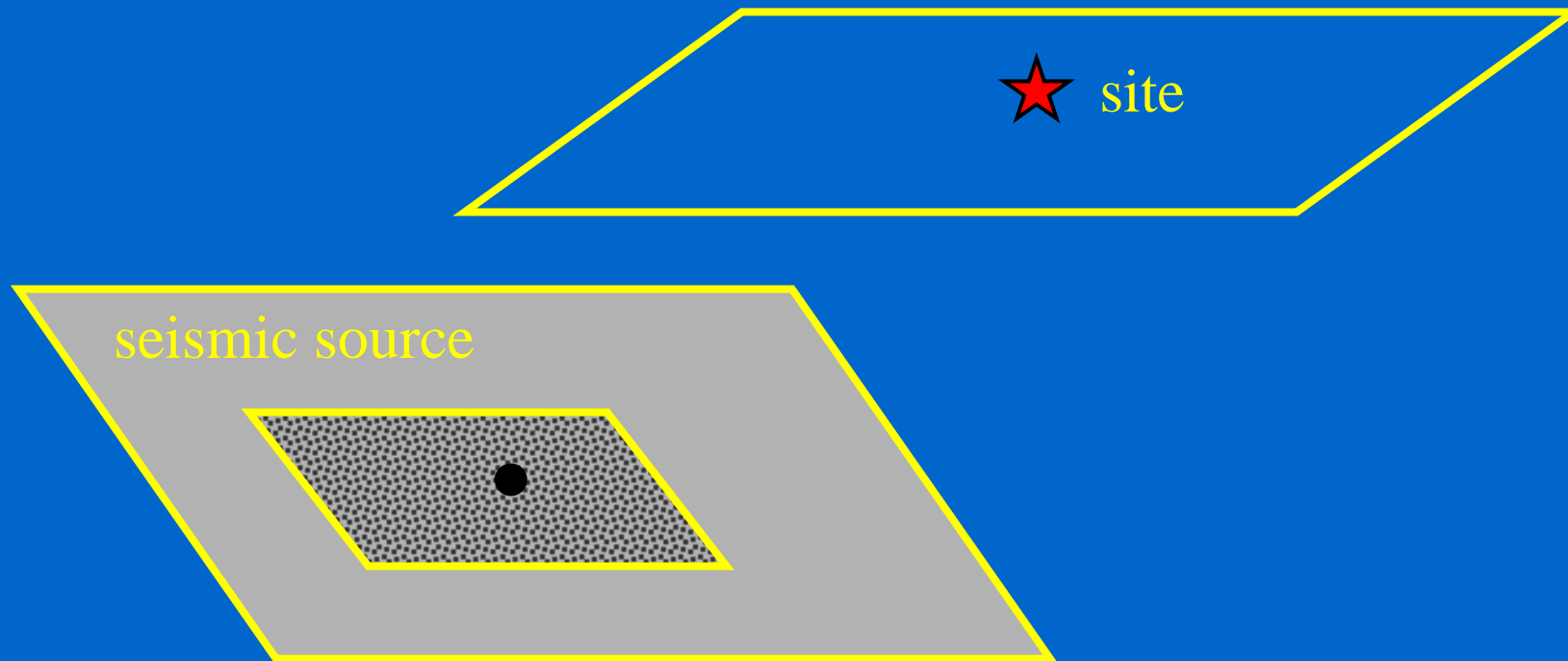
Seismological model

Finite-fault stochastic Green's function method



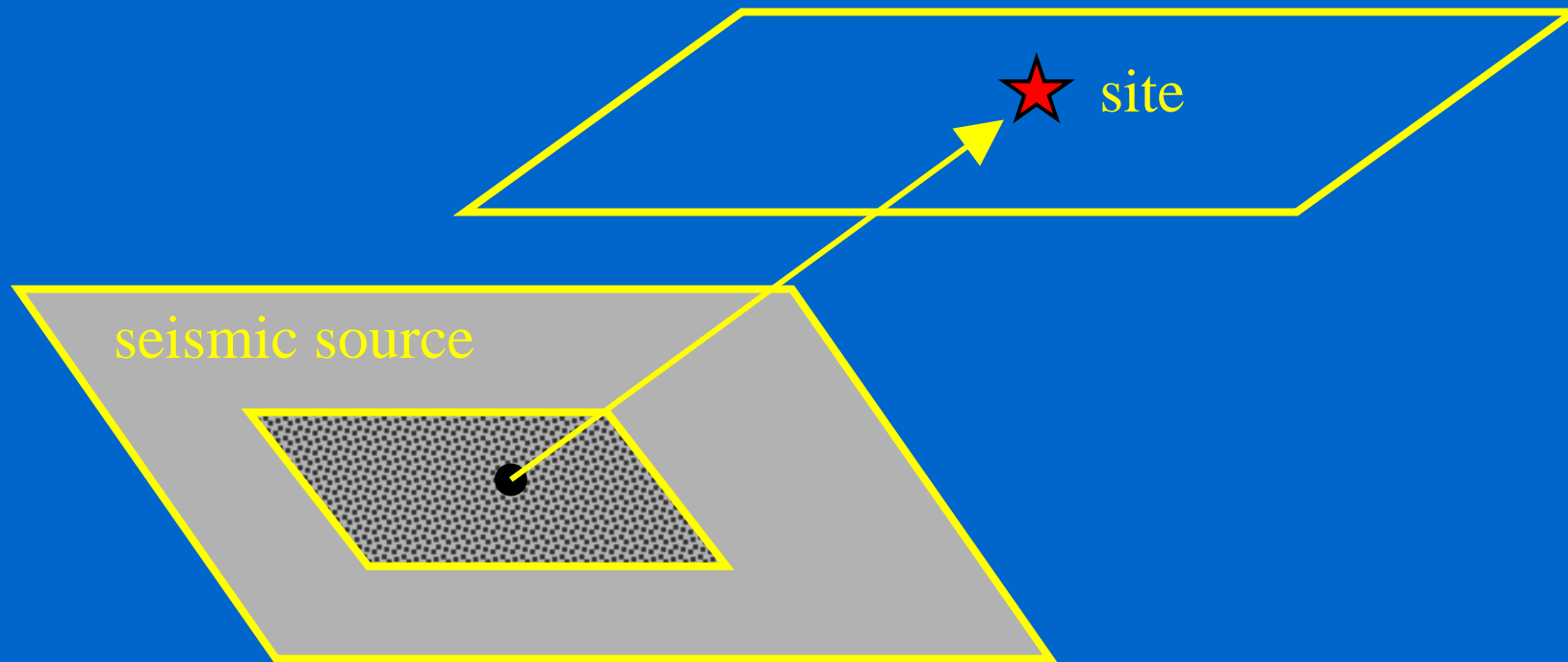
Seismological model

Finite-fault stochastic Green's function method



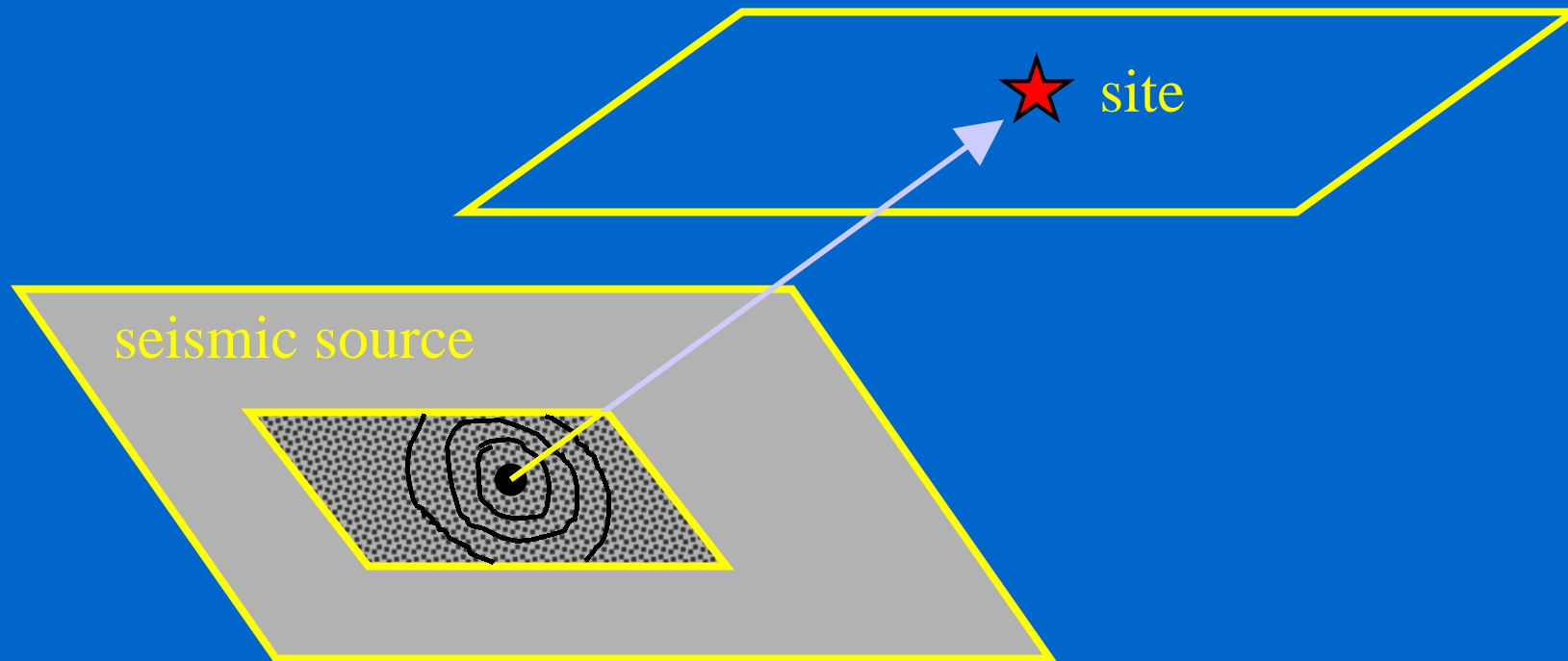
Seismological model

Finite-fault stochastic Green's function method



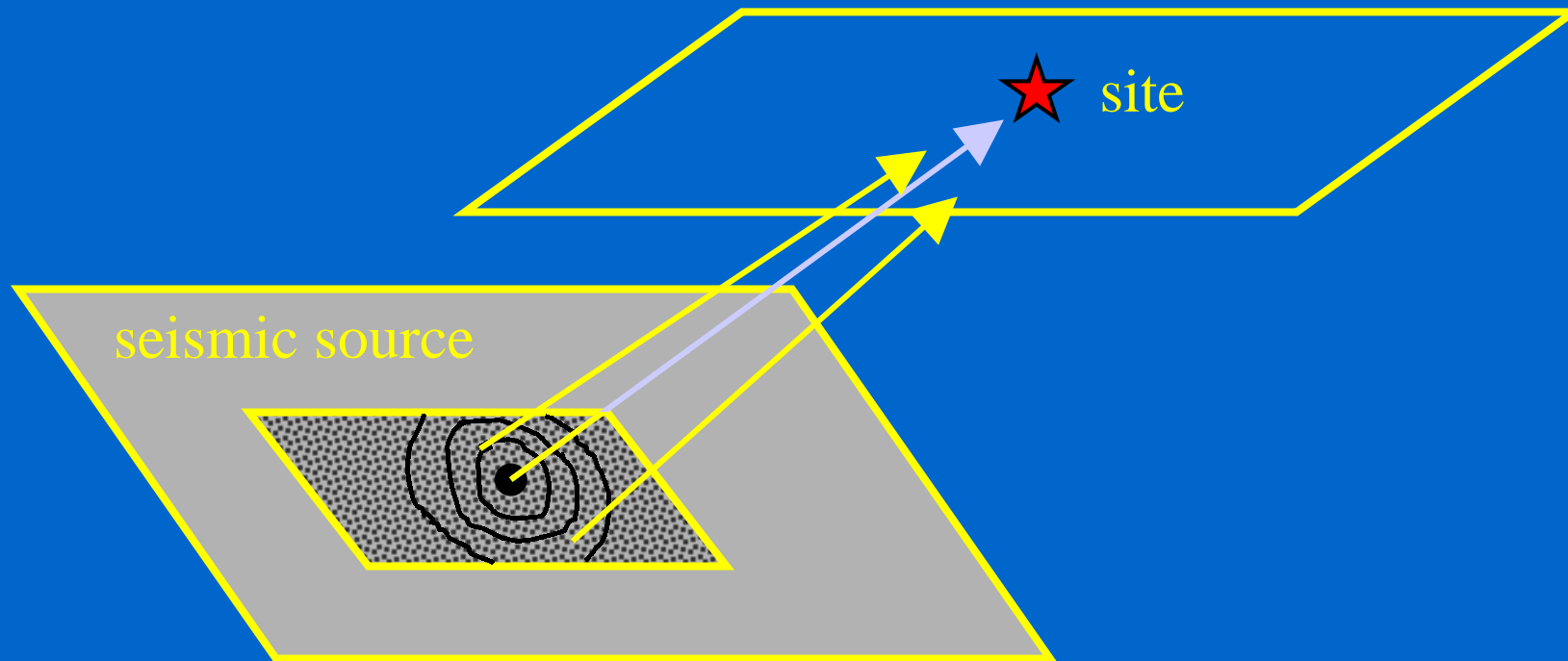
Seismological model

Finite-fault stochastic Green's function method



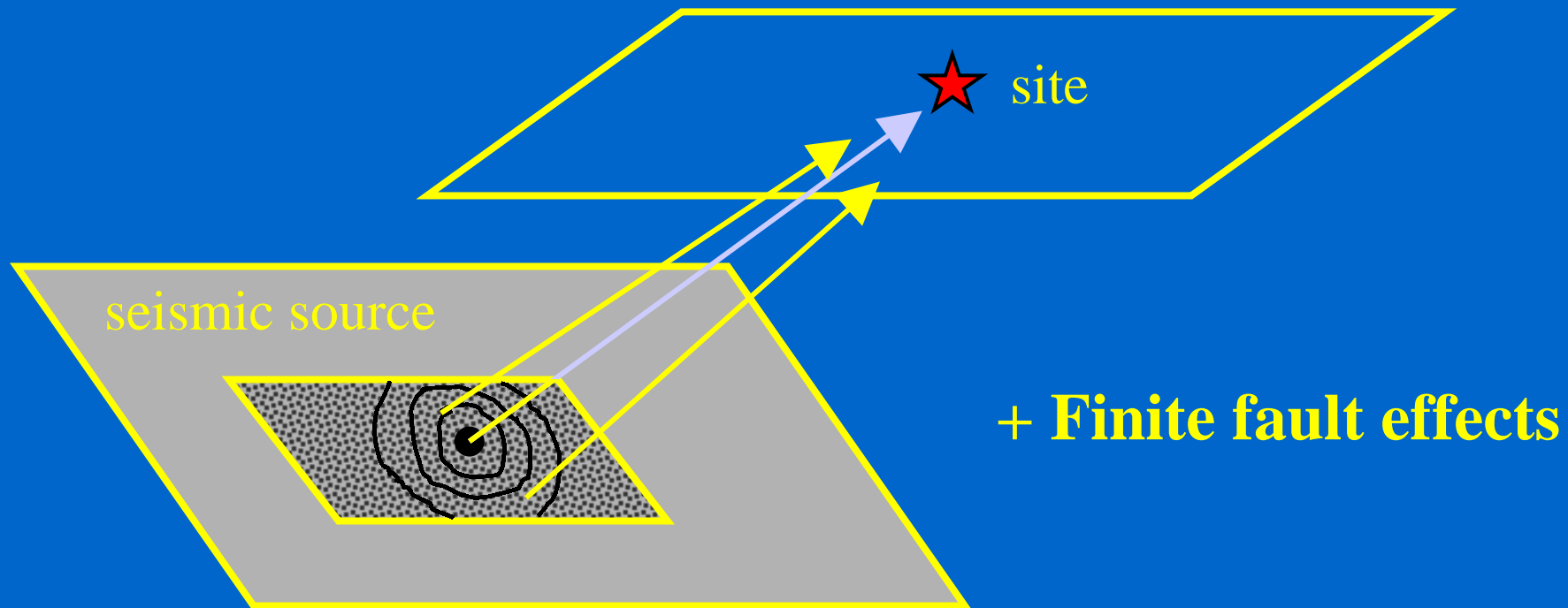
Seismological model

Finite-fault stochastic Green's function method



Seismological model

Finite-fault stochastic Green's function method



Application to a building in Tokyo



Kozo Keikaku Engineering



Application to a building in Tokyo



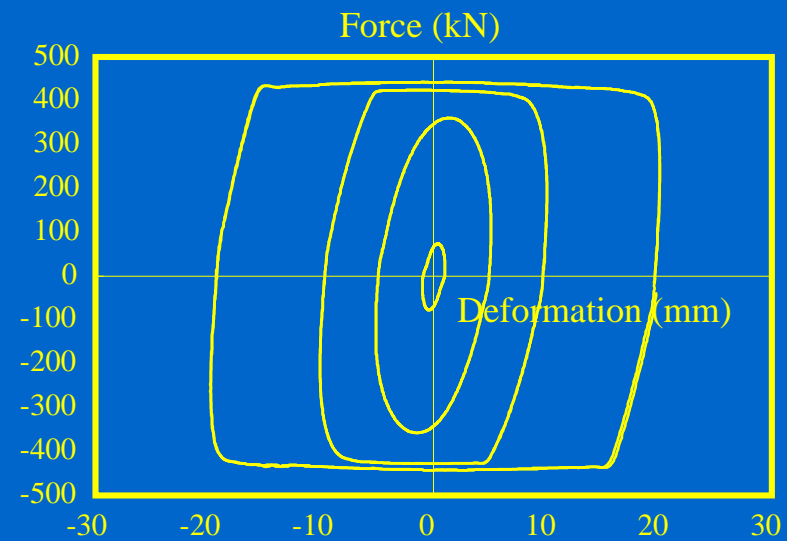
Kozo Keikaku Engineering



Application to a building in Tokyo



Kozo Keikaku Engineering

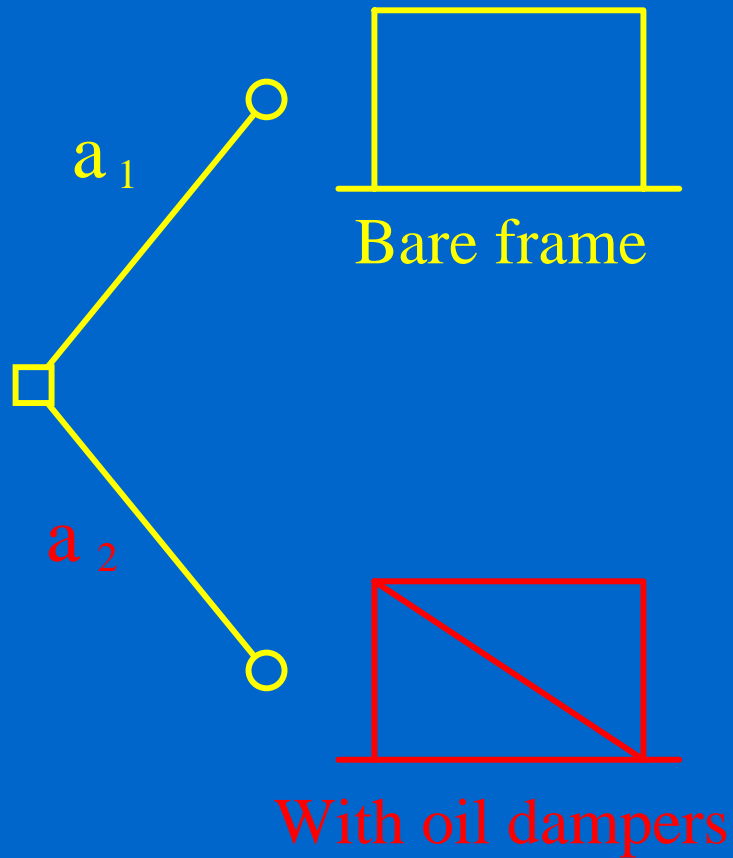


Hysteresis loops

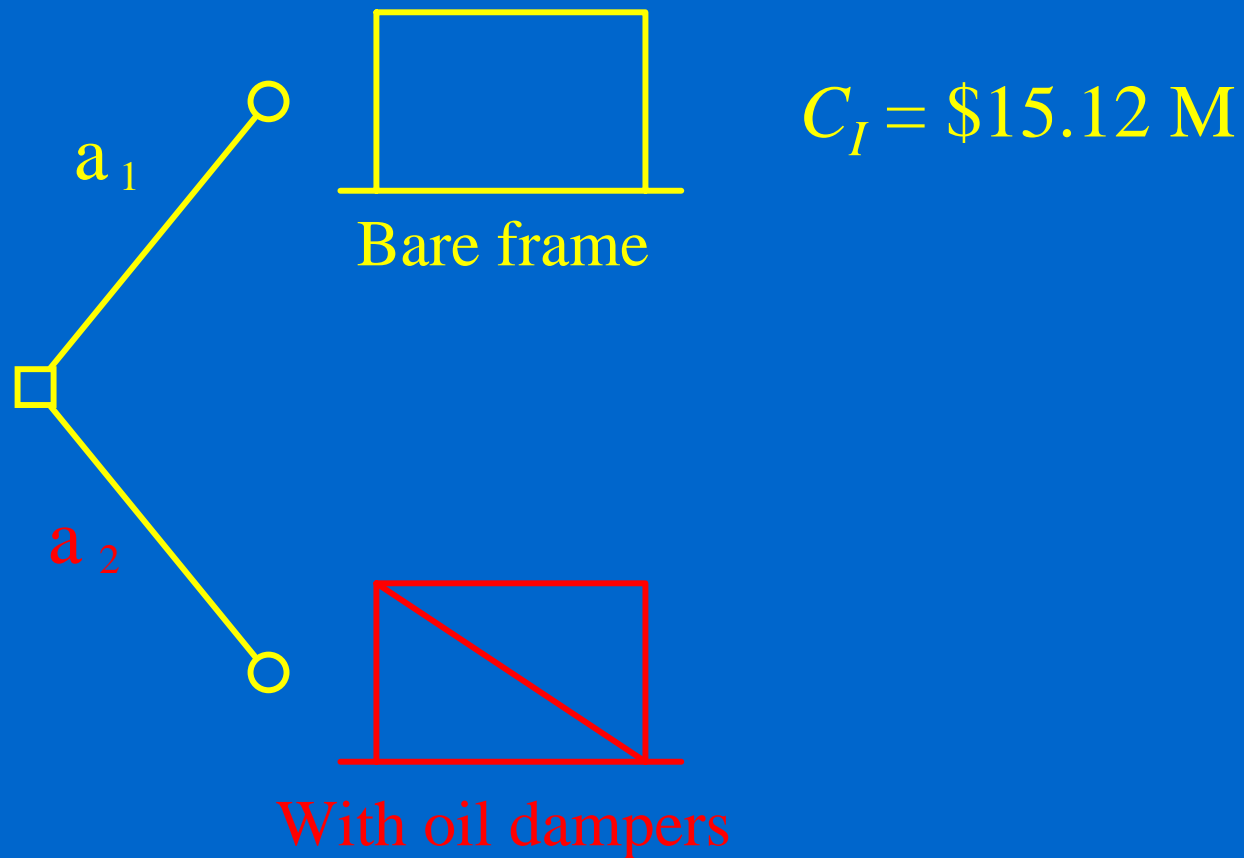
6/17



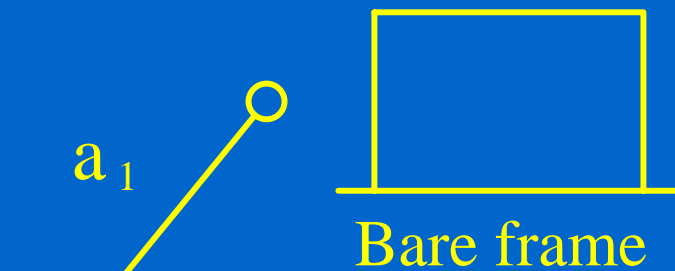
Decision making between two alternatives



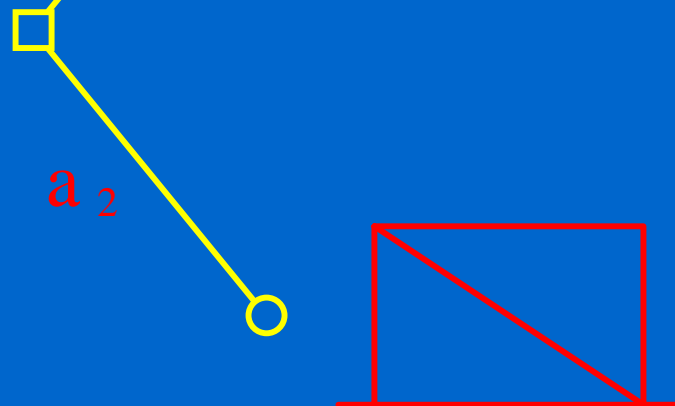
Decision making between two alternatives



Decision making between two alternatives



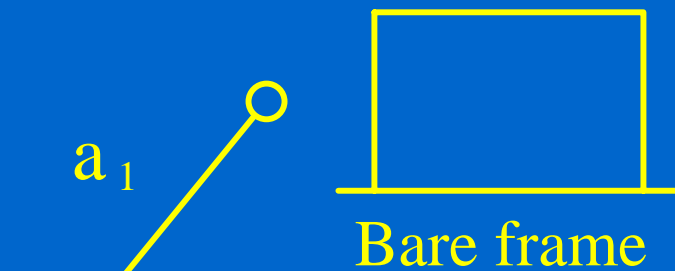
$$C_I = \$15.12 \text{ M}$$



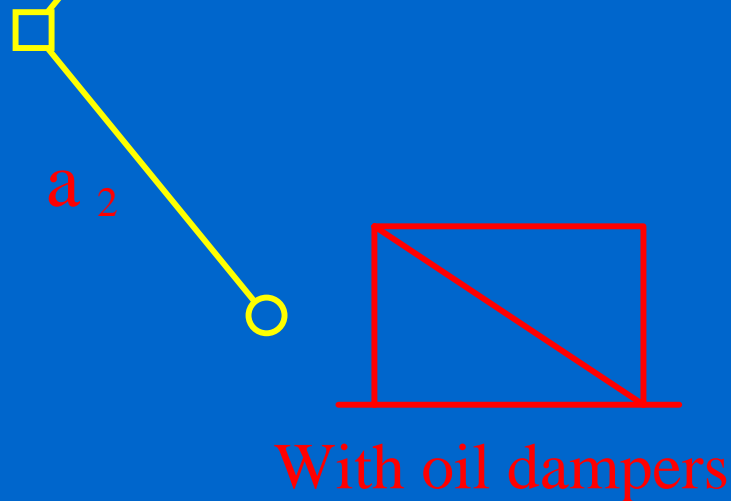
$$C_I = \$15.12 \text{ M} + \$0.36 \text{ M}$$



Decision making between two alternatives



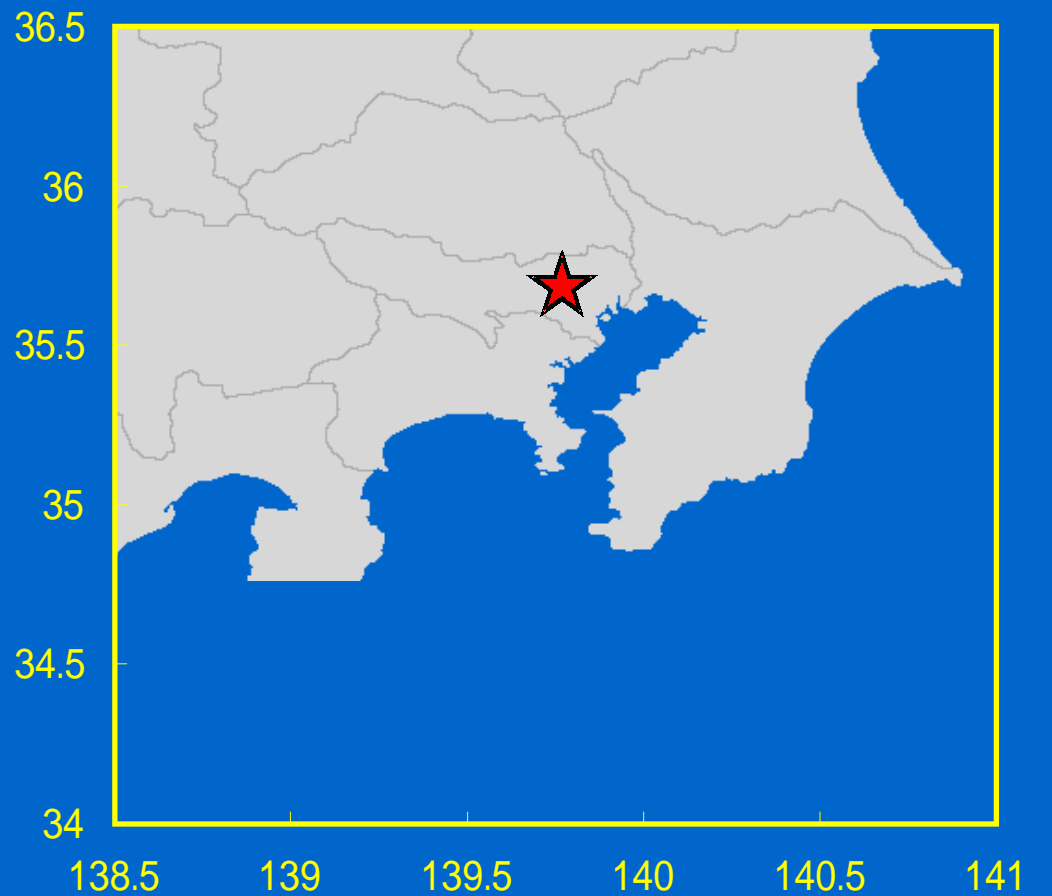
$$C_I = \$15.12 \text{ M}$$



$$\begin{aligned} C_I &= \$15.12 \text{ M} + \$0.36 \text{ M} \\ &= \$15.48 \text{ M} \end{aligned}$$



Building site & seismic source

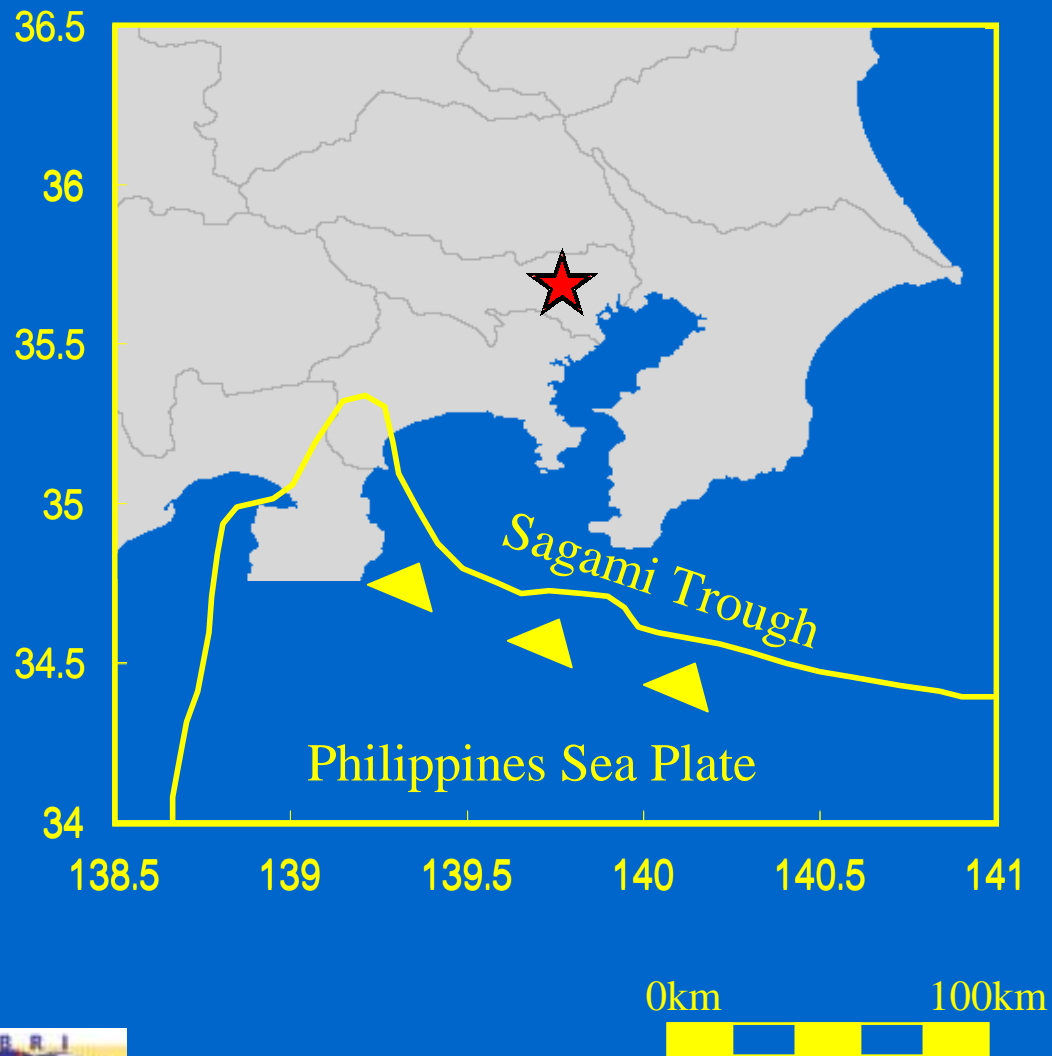


0km 100km

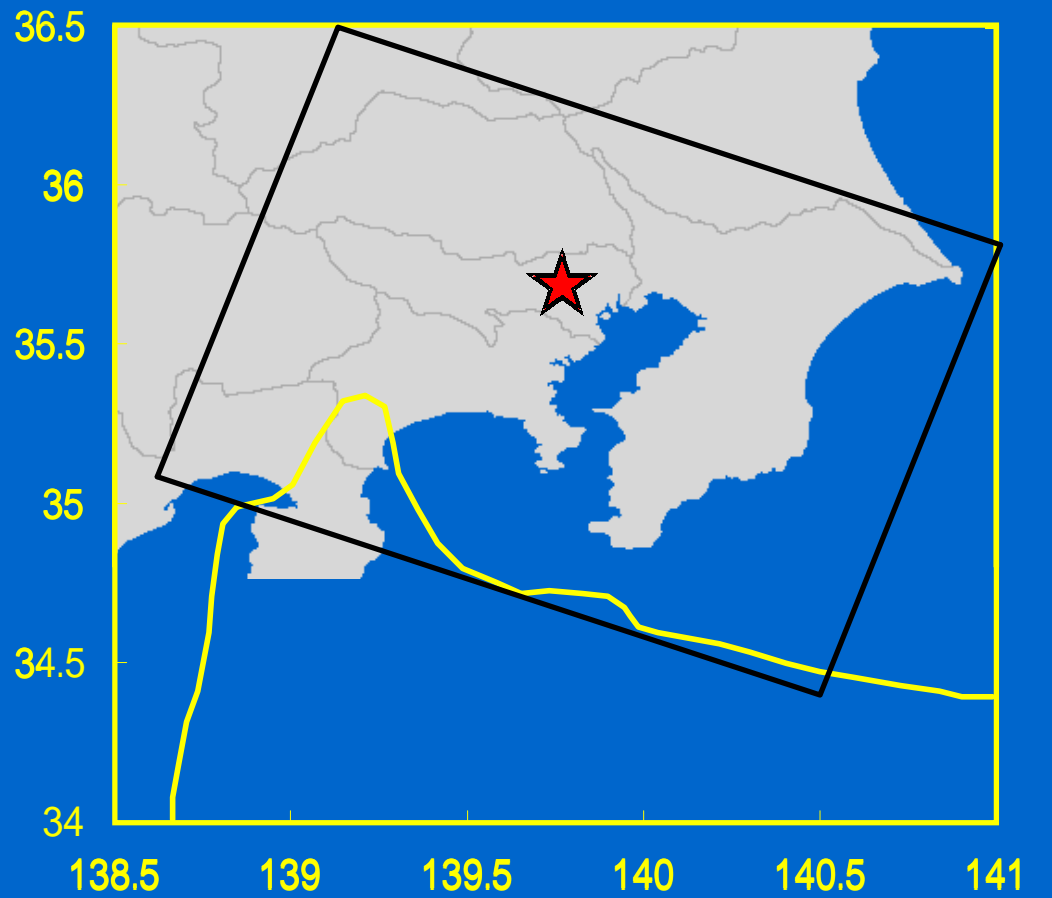
A scale bar consisting of a yellow rectangle divided into four equal segments, with the text '0km' at the left end and '100km' at the right end.



Building site & seismic source



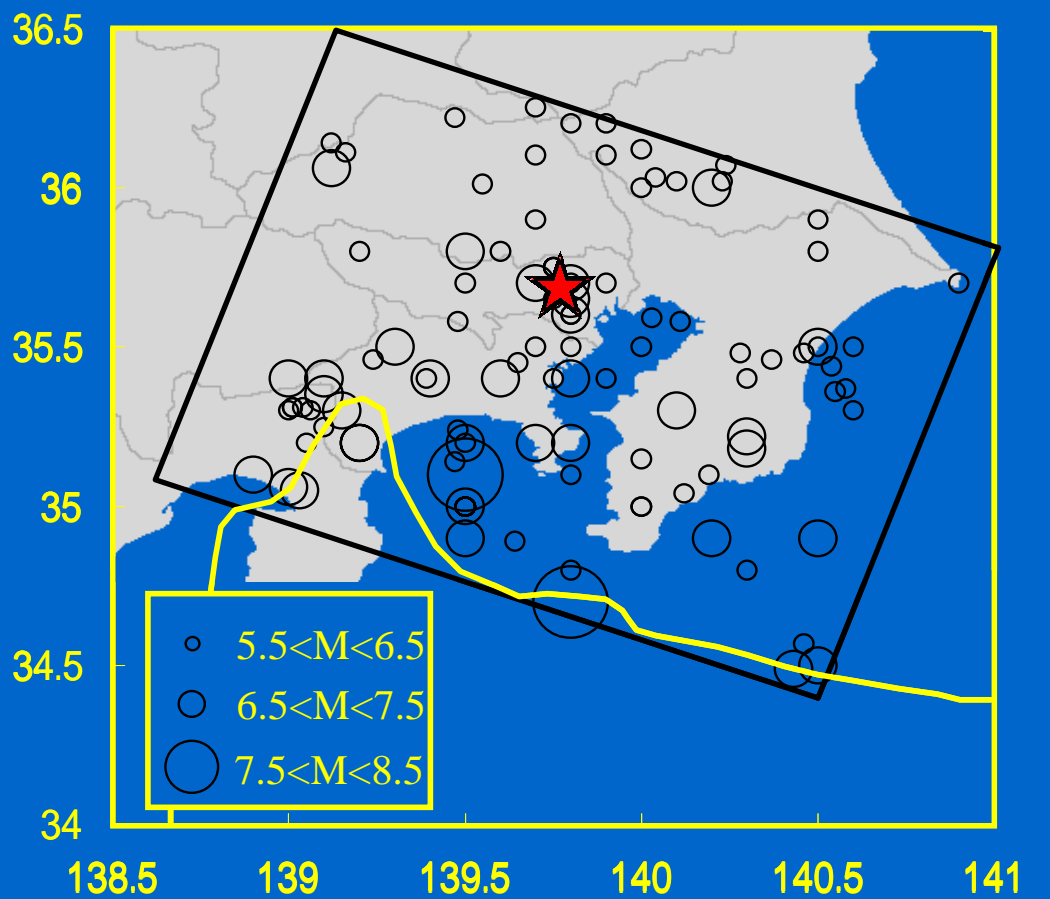
Building site & seismic source



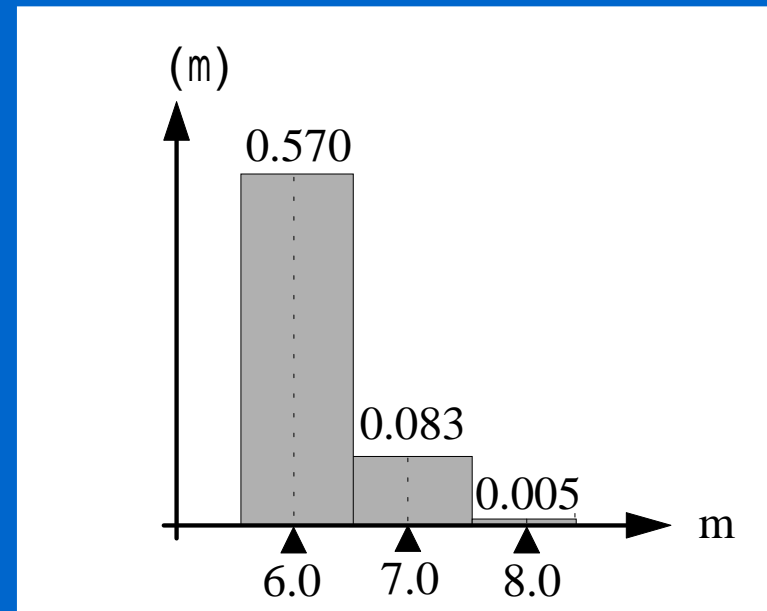
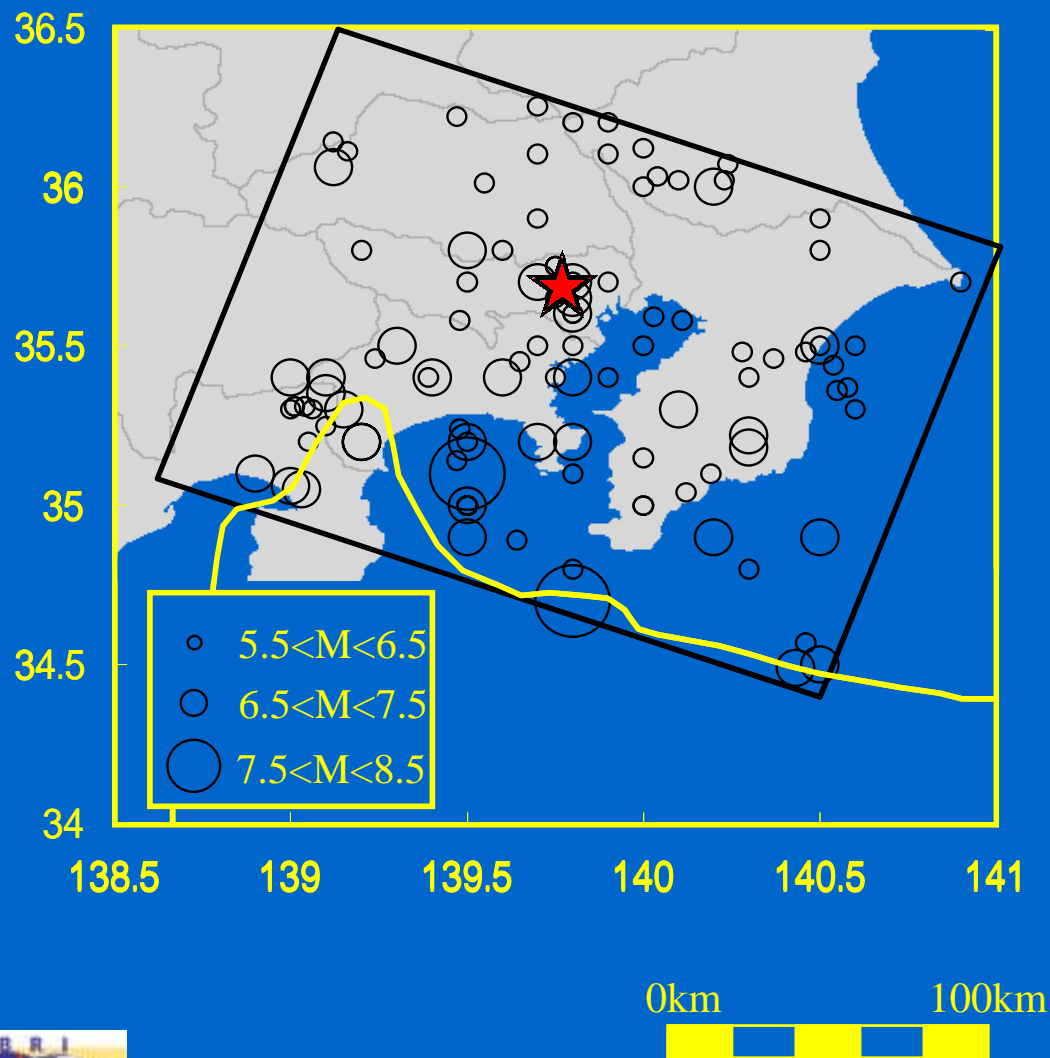
0km 100km



Building site & seismic source



Building site & seismic source

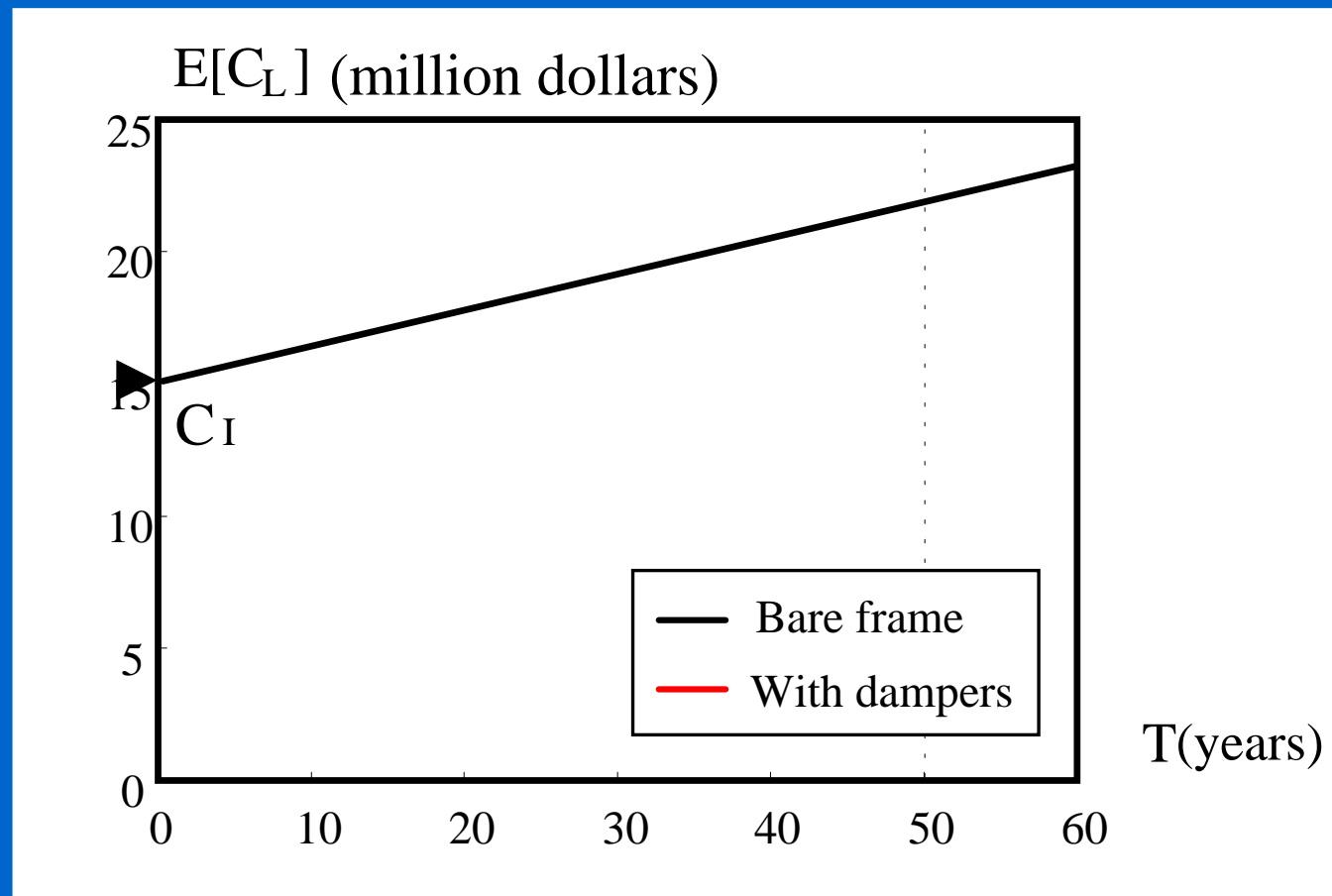


magnitude – annual rate



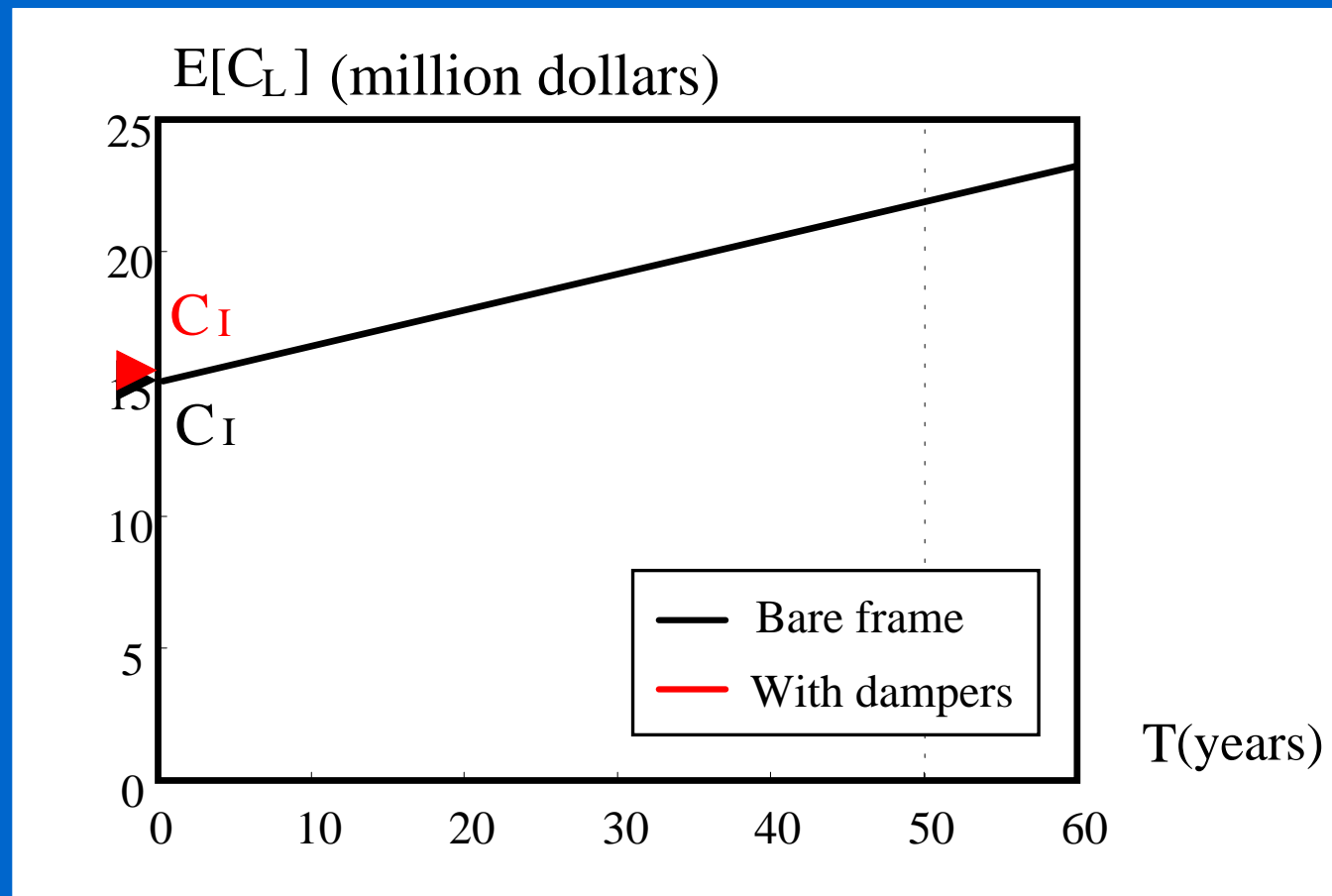
Lifetime vs. expected life-cycle cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



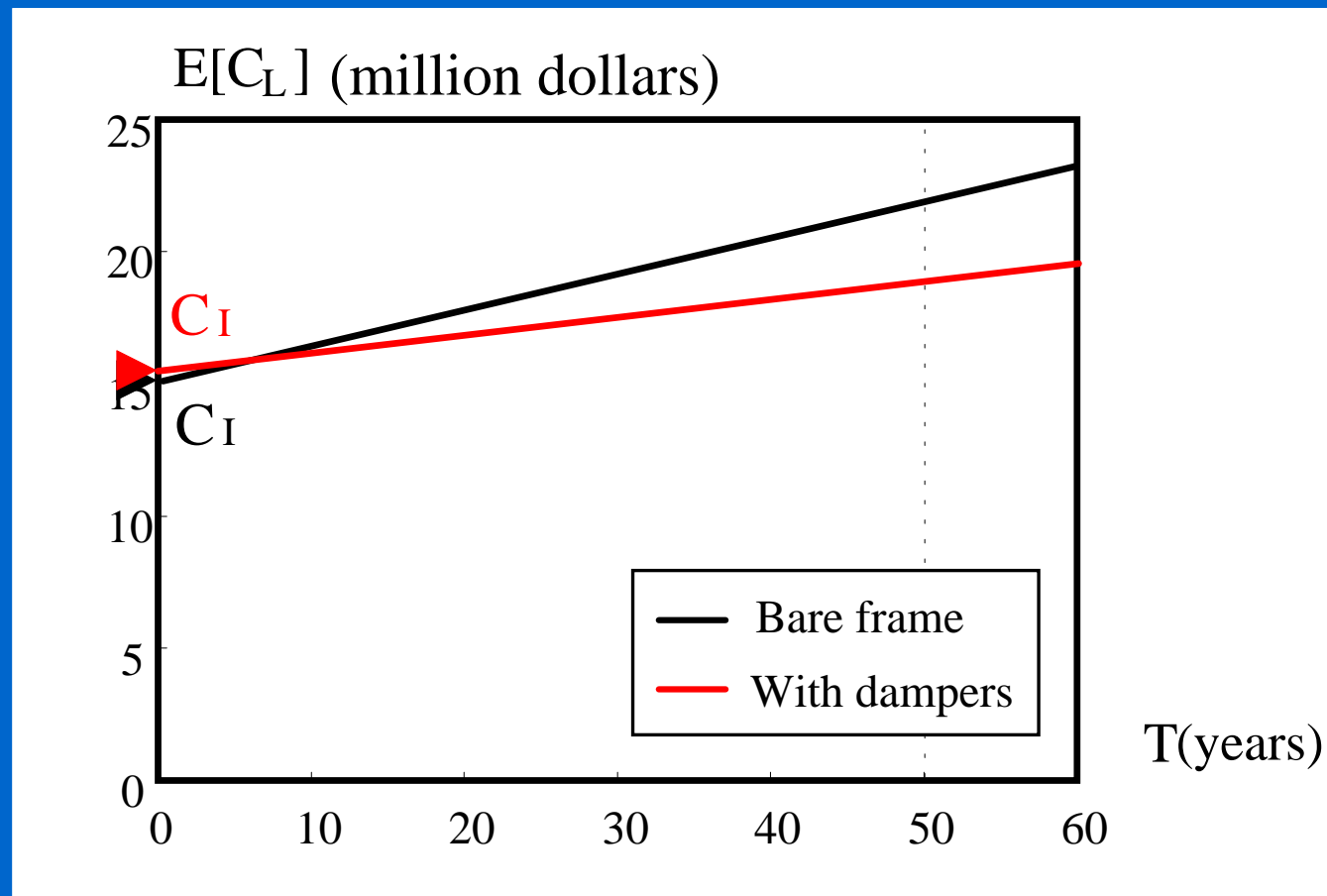
Lifetime vs. expected life-cycle cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



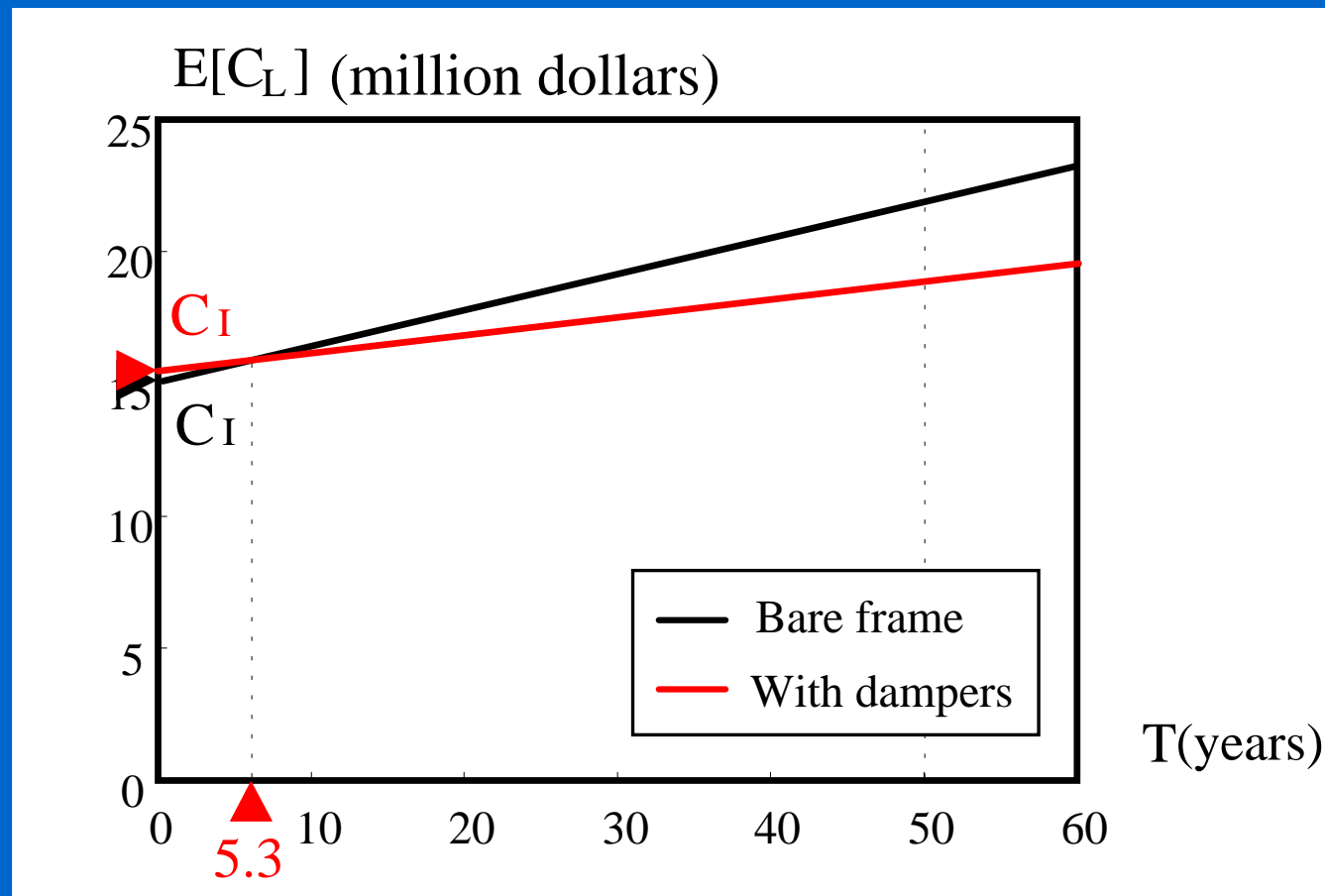
Lifetime vs. expected life-cycle cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



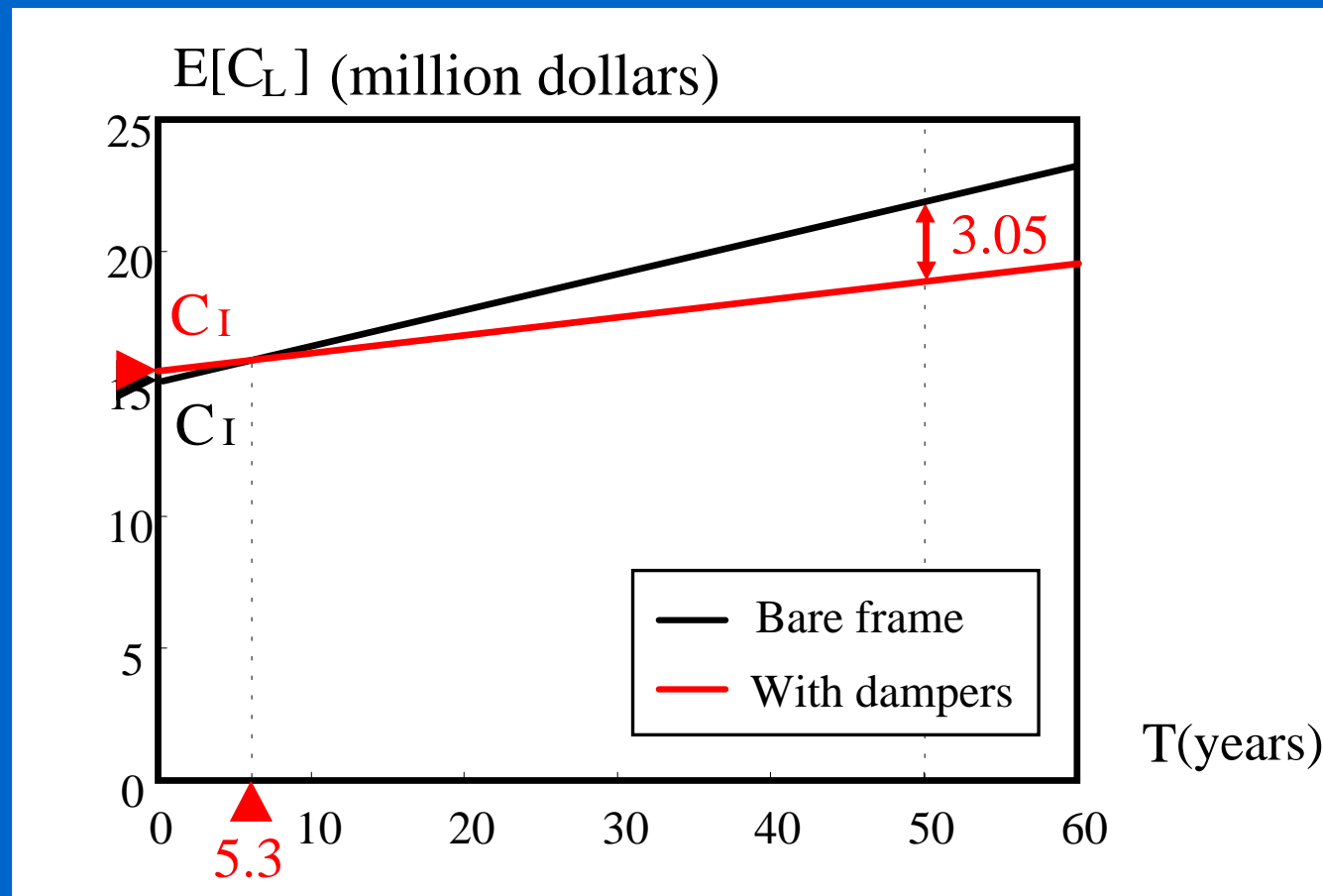
Lifetime vs. expected life-cycle cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



Lifetime vs. expected life-cycle cost

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



Generalization for non-Poisson renewal model

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$



Generalization for non-Poisson renewal model

$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$

+ **Non-Poisson renewal model, e.g., BPT model**



Generalization for non-Poisson renewal model

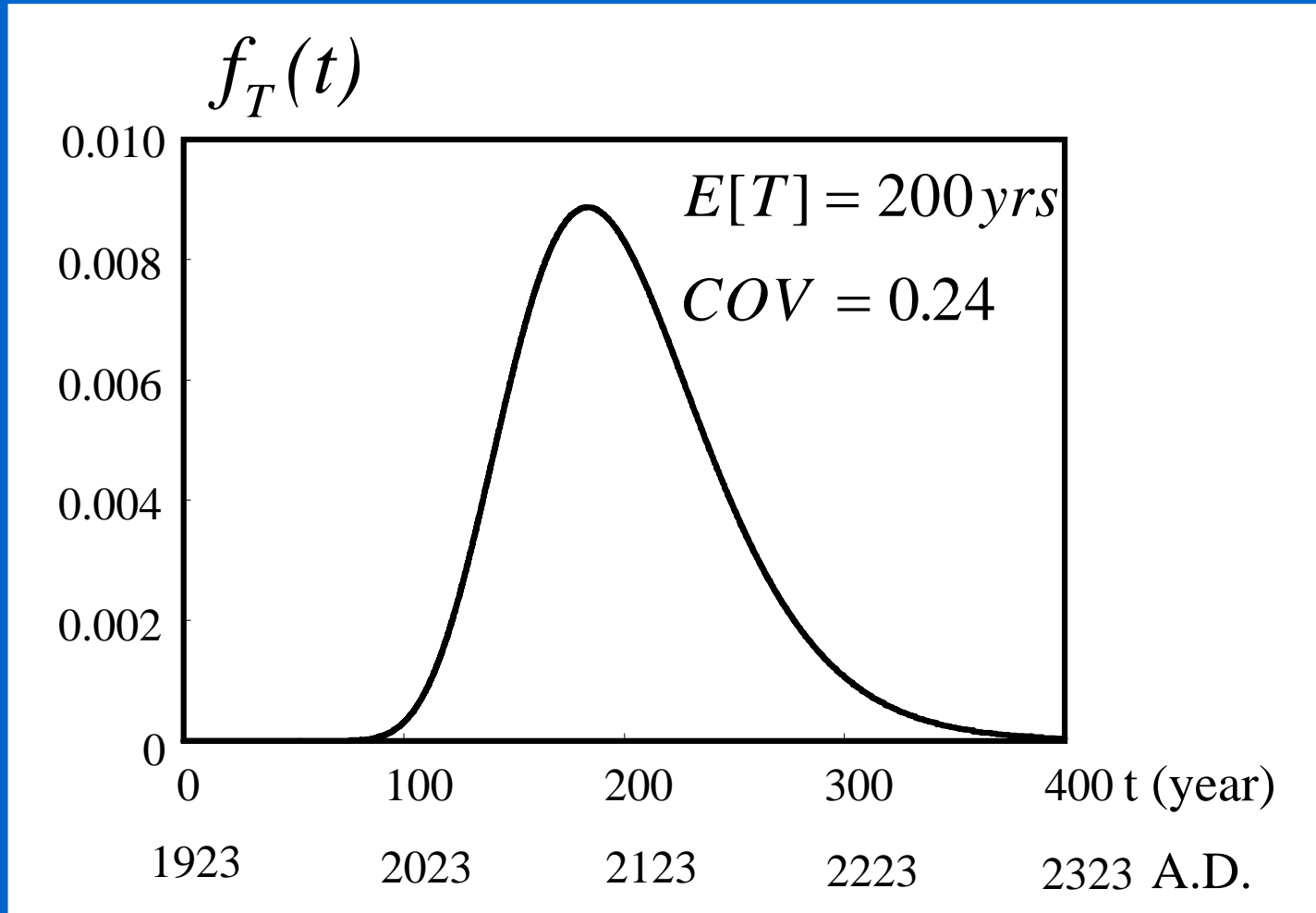
$$E[C_L] = C_I + \Delta T \times \sum_{\text{all sources}} \sum_{j=1}^K v(m_j) \cdot E[C_D(m_j)]$$

+ **Non-Poisson renewal model, e.g., BPT model**

$$E[C_L] = C_I + \sum_{\text{all sources}} \sum_{j=1}^K E[C_D(m_j)] \int_{t_0}^{t_0 + \Delta T} \sum_{n=1}^{\infty} f_{T_{nth}}(m_j, t | T > t_0) dt$$



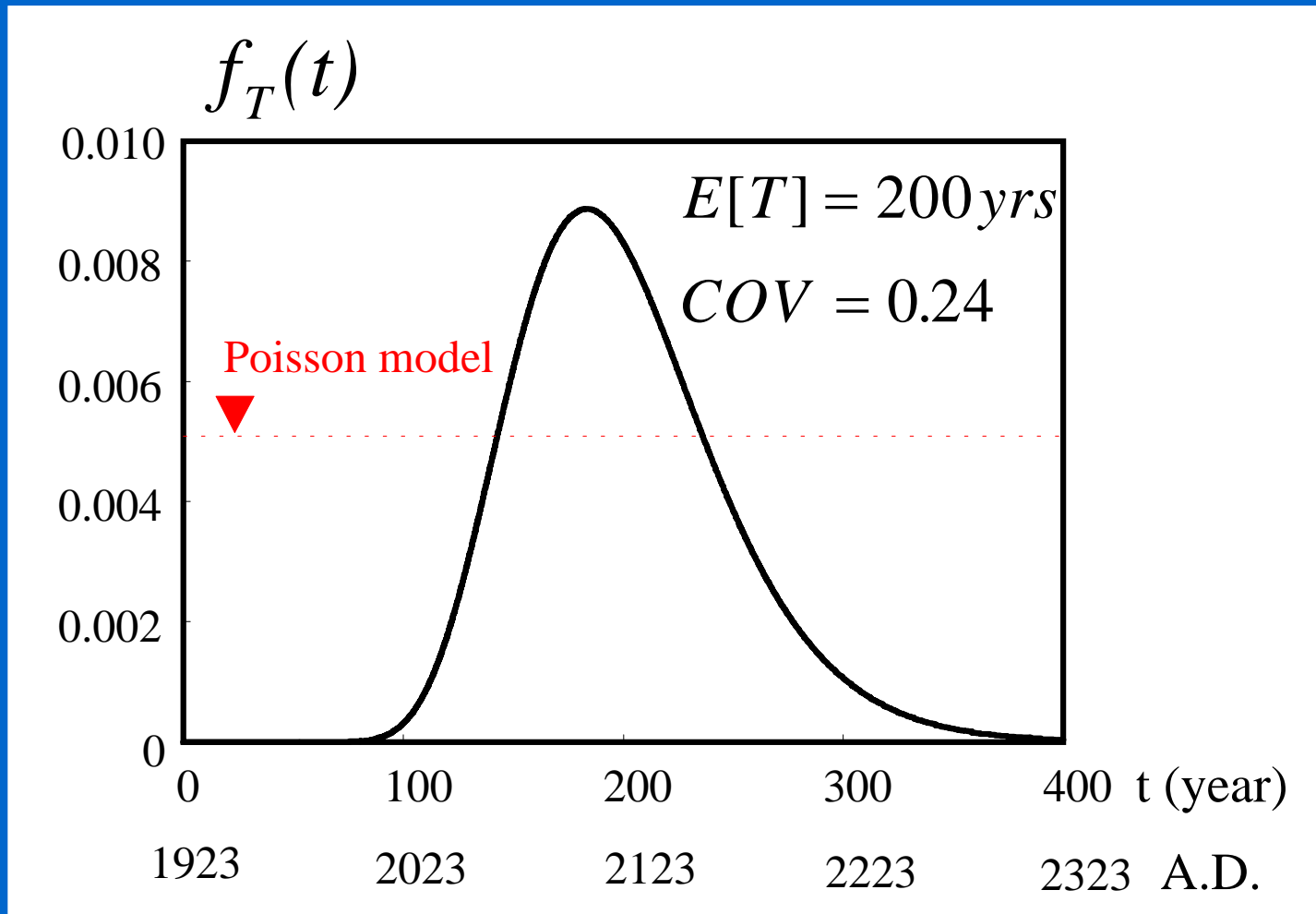
Brownian Passage Time model (WGCEP, HERP)



PDF of waiting time to the next earthquake



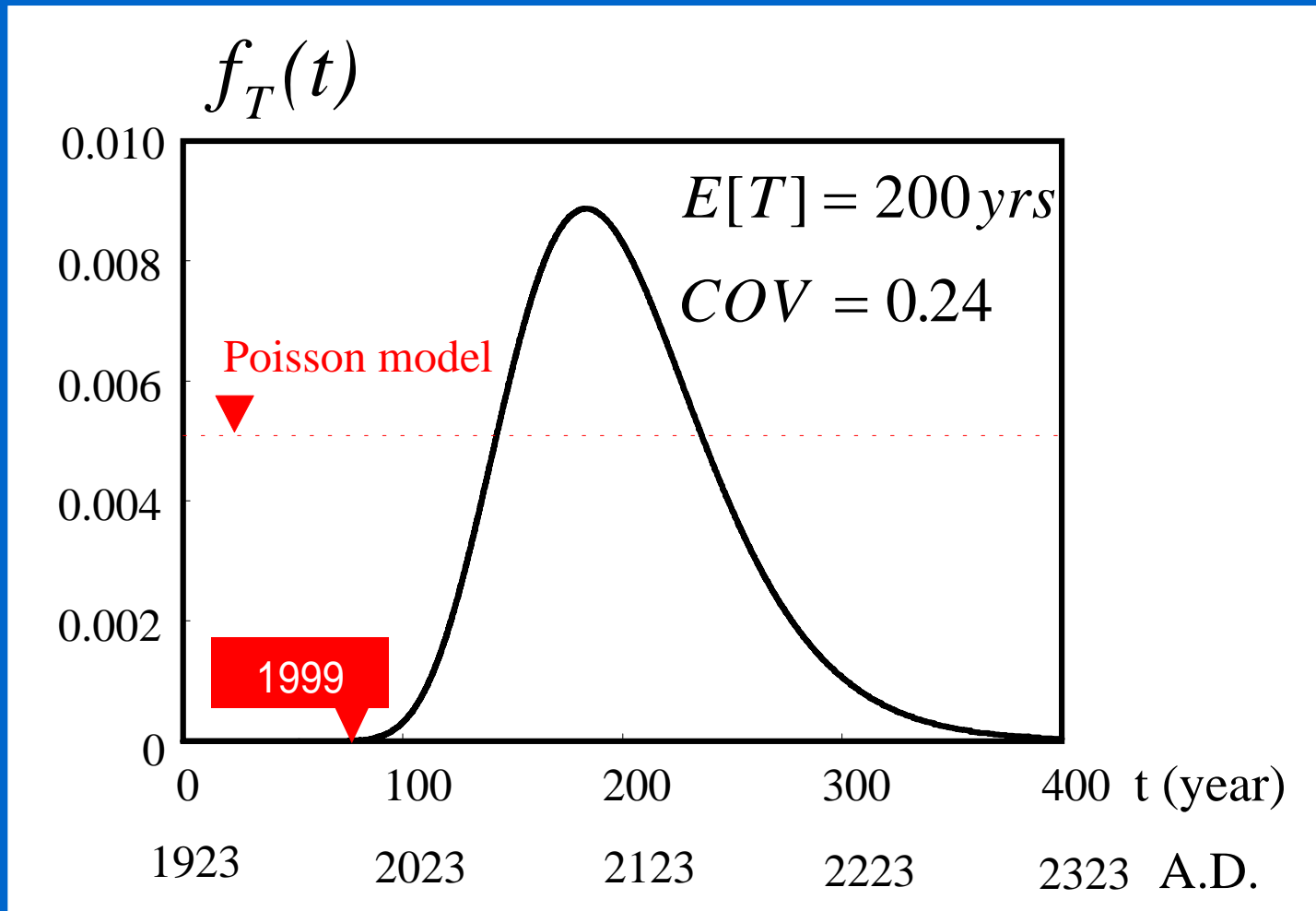
Brownian Passage Time model (WGCEP, HERP)



PDF of waiting time to the next earthquake



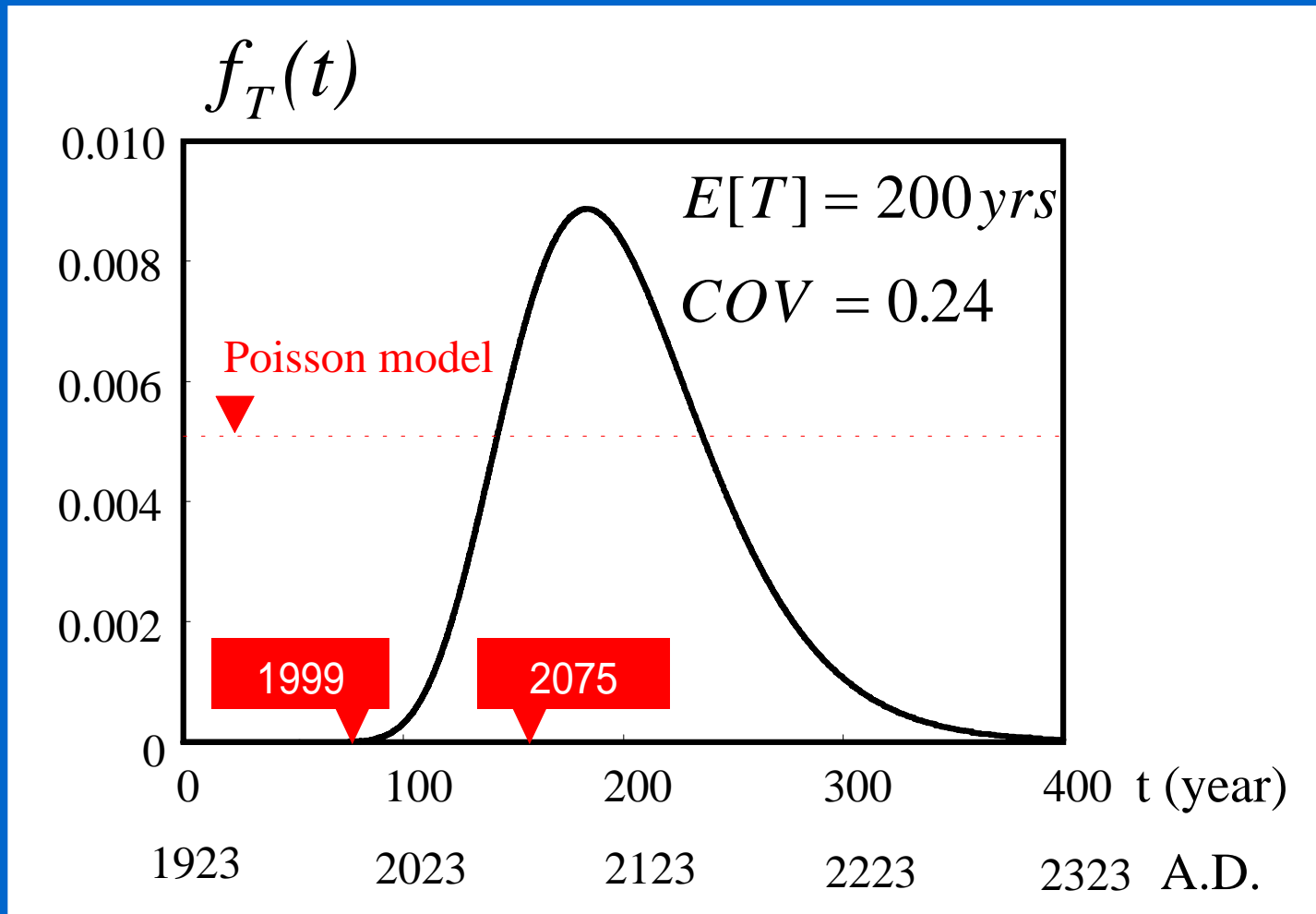
Brownian Passage Time model (WGCEP, HERP)



PDF of waiting time to the next earthquake



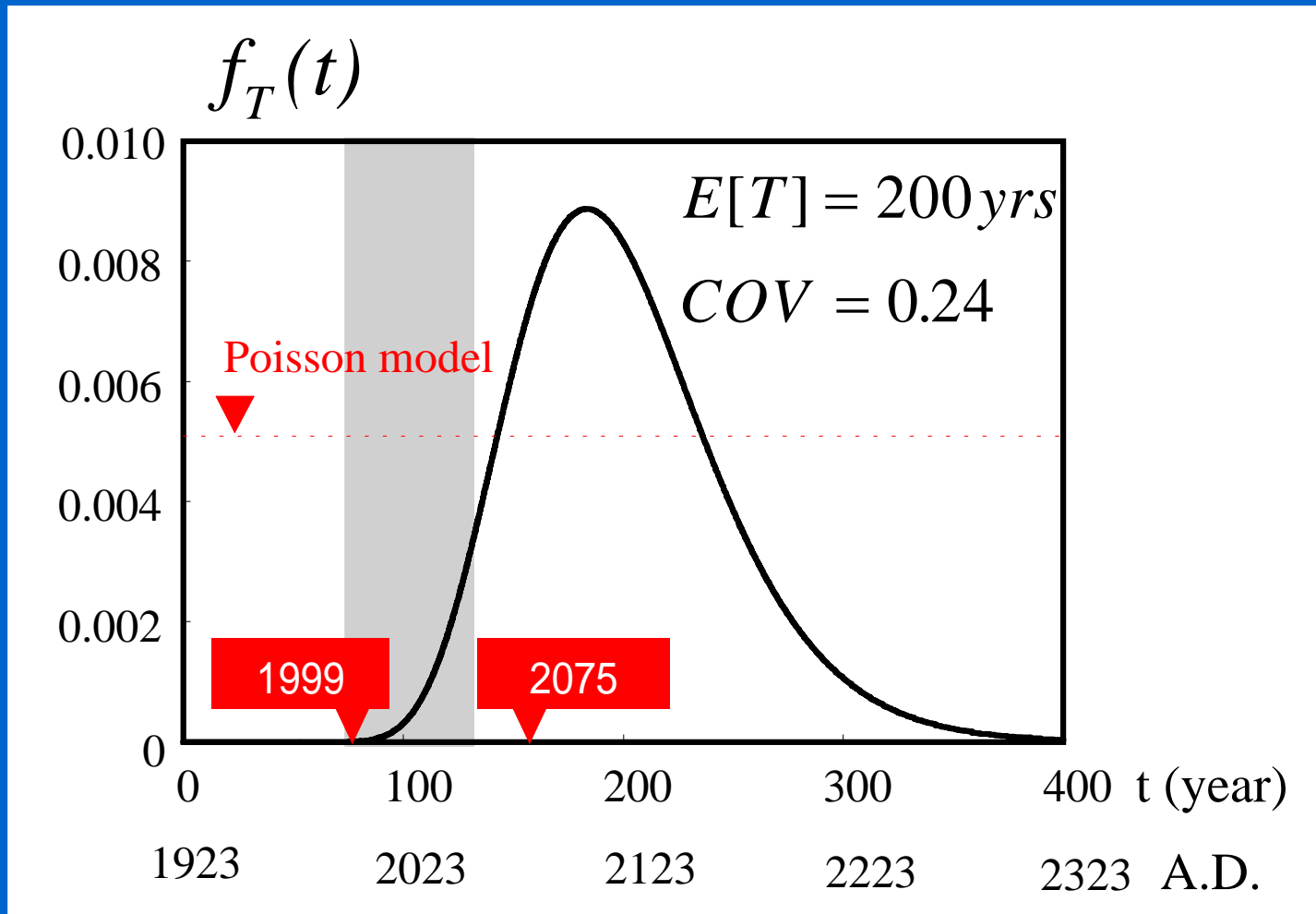
Brownian Passage Time model (WGCEP, HERP)



PDF of waiting time to the next earthquake



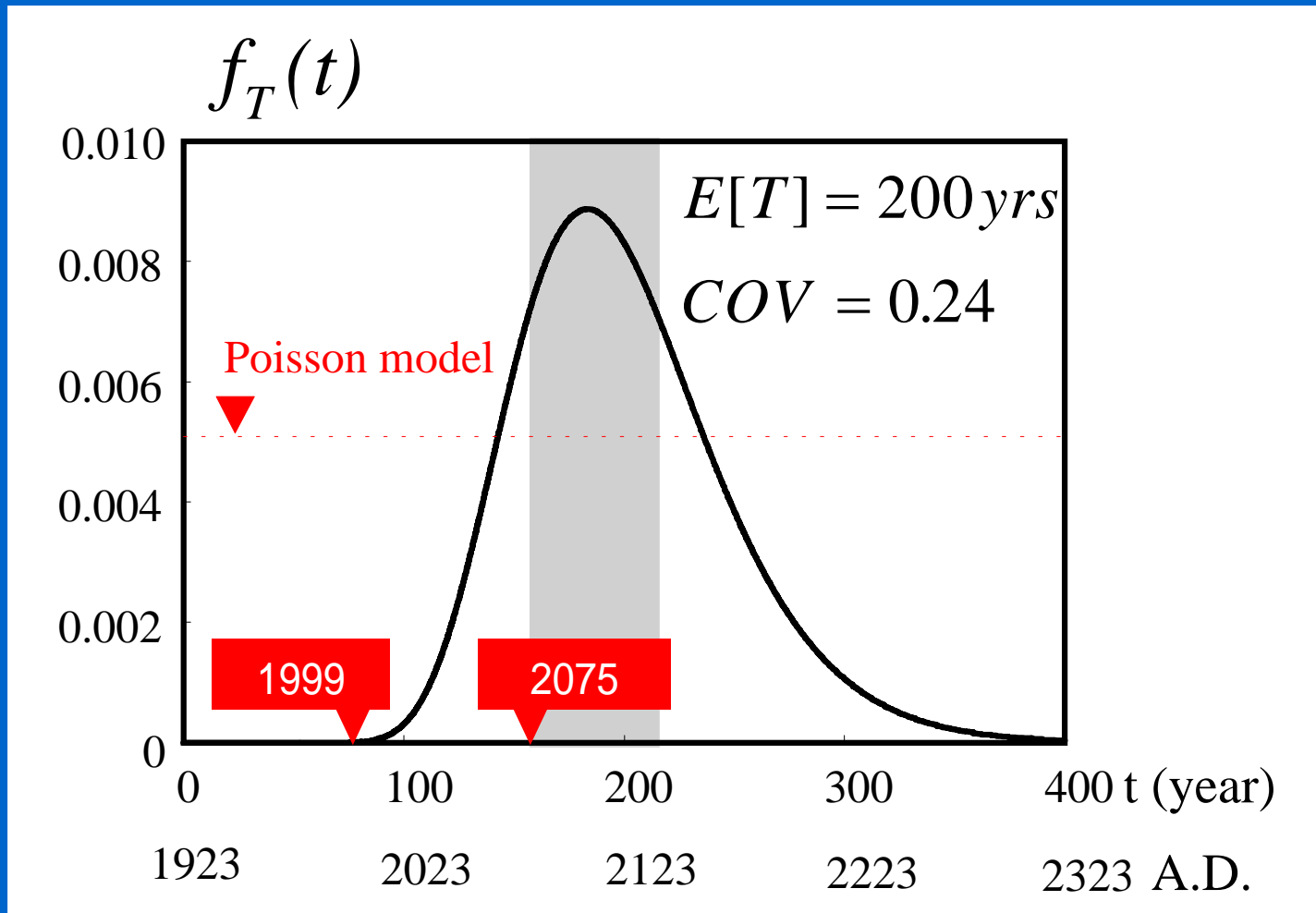
Brownian Passage Time model (WGCEP, HERP)



PDF of waiting time to the next earthquake



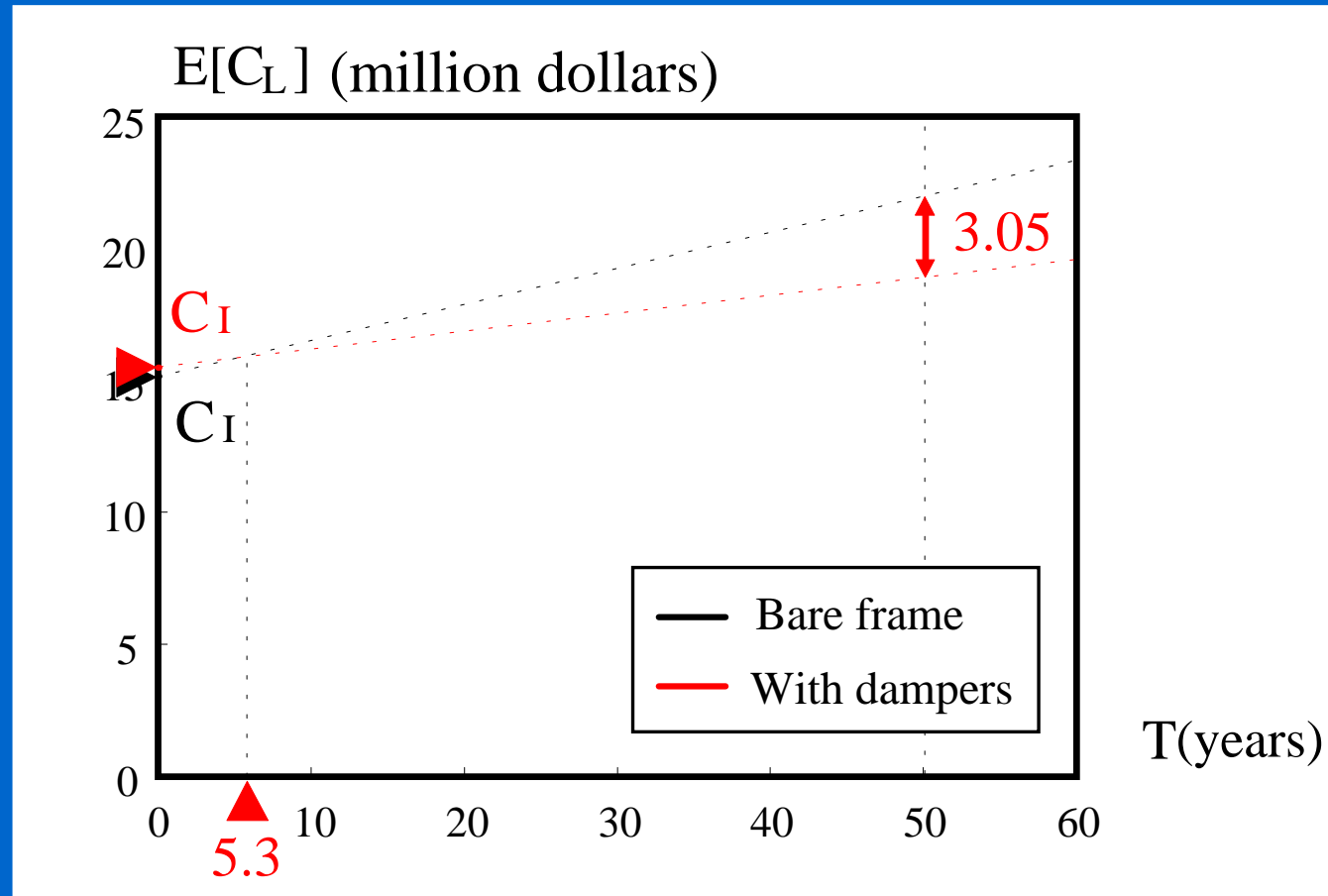
Brownian Passage Time model (WGCEP, HERP)



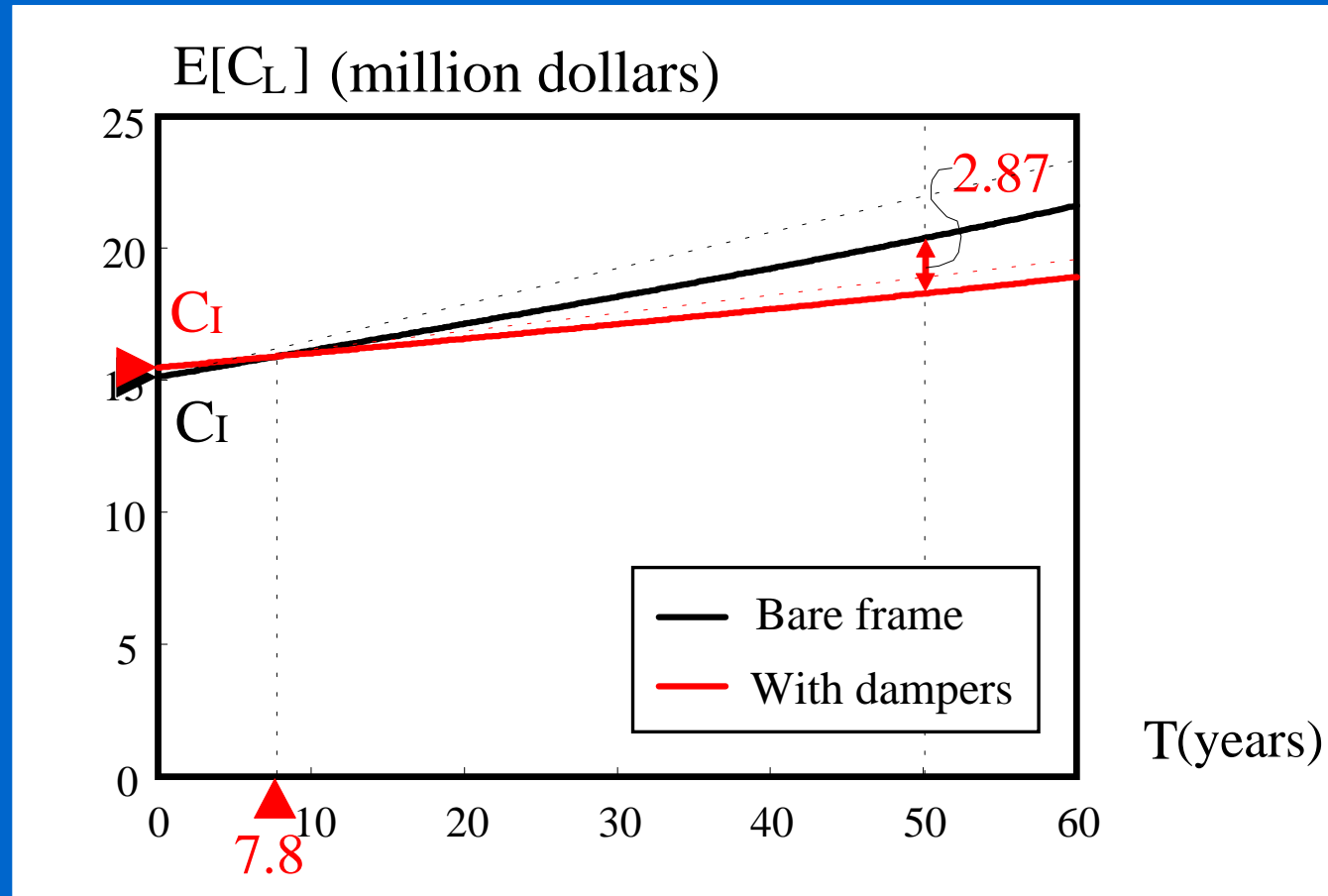
PDF of waiting time to the next earthquake



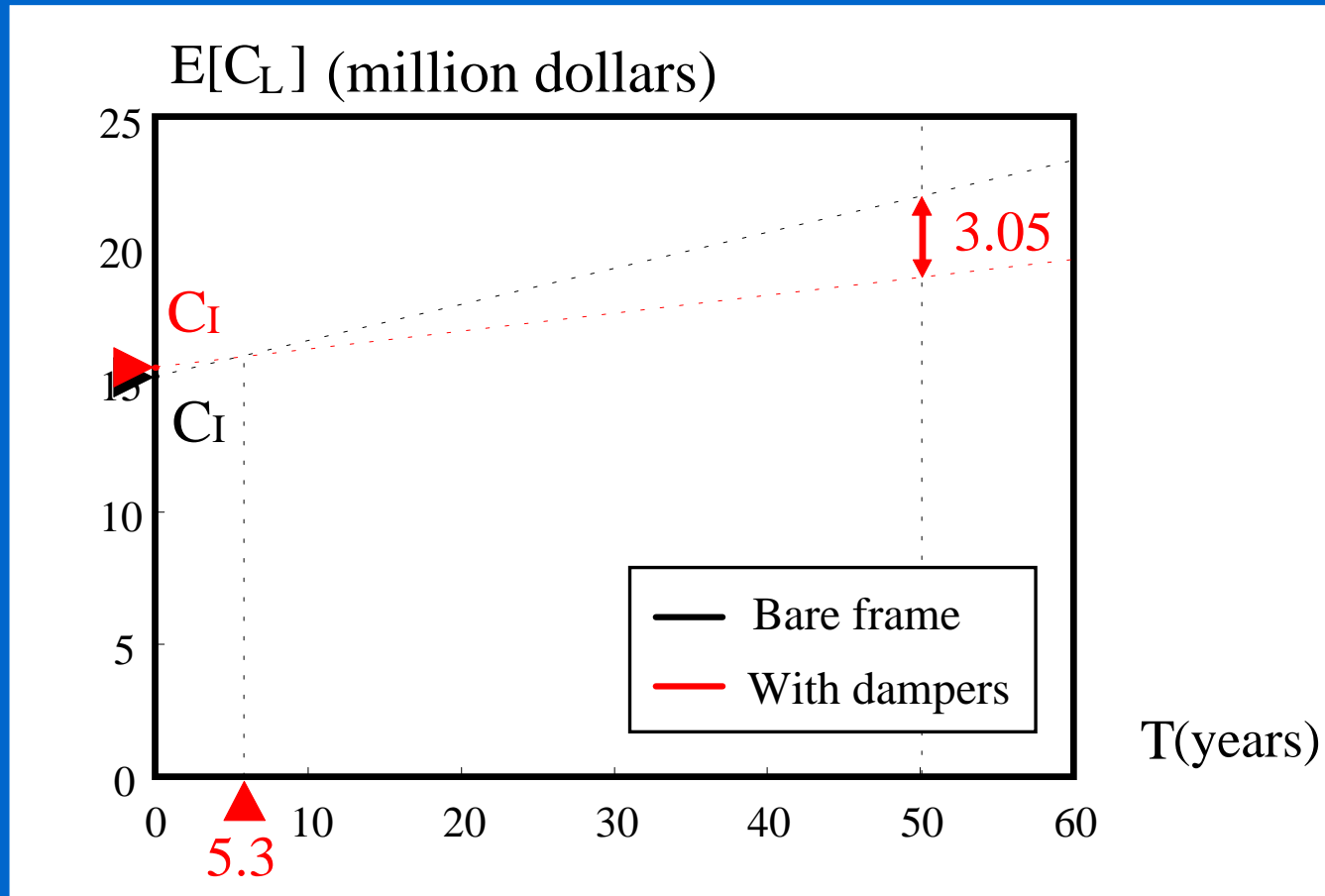
Lifetime vs. expected LCC (BPT model: $t_0 = \text{A.D.1999}$)



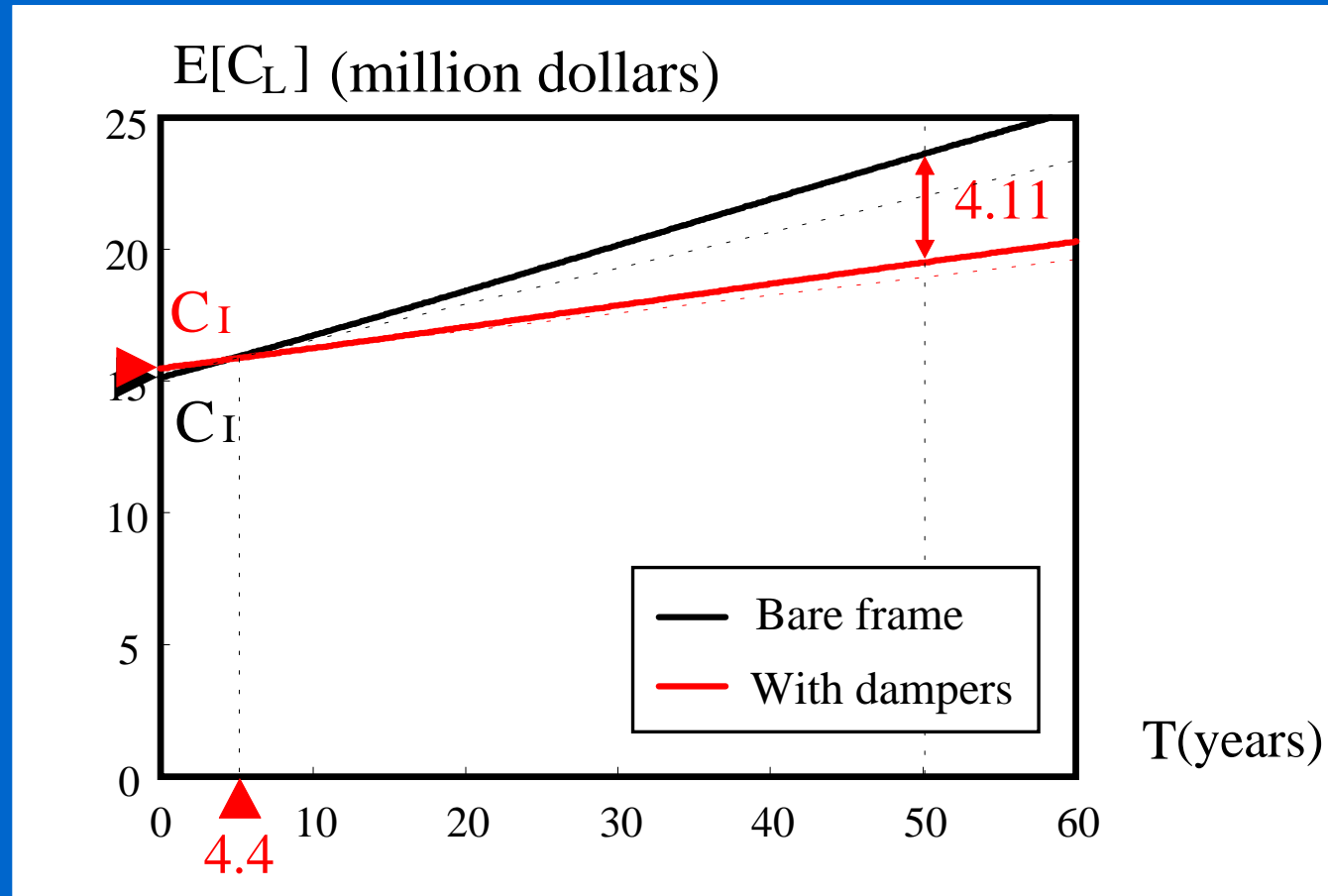
Lifetime vs. expected LCC (BPT model: $t_0 = \text{A.D.1999}$)



Lifetime vs. expected LCC (BPT model: $t_0 = \text{A.D.2075}$)



Lifetime vs. expected LCC (BPT model: $t_0 = \text{A.D.2075}$)



Conclusions (Basic formulation)

Expected life-cycle cost is formulated as follows.

$$E[C_L] = C_I + \sum_{\text{all sources}} \sum_{j=1}^K E[C_D(m_j)] \int_{t_0}^{t_0 + \Delta T} \sum_{n=1}^{\infty} f_{T_{nth}}(m_j, t | T > t_0) dt$$



Conclusions (Basic formulation)

Expected life-cycle cost is formulated as follows.

Earthquake probability estimation

$$E[C_L] = C_I + \sum_{\text{all sources}} \sum_{j=1}^K E[C_D(m_j)] \int_{t_0}^{t_0 + \Delta T} \sum_{n=1}^{\infty} f_{T_{nth}}(m_j, t | T > t_0) dt$$



Conclusions (Basic formulation)

Expected life-cycle cost is formulated as follows.

$$E[C_L] = C_I + \sum_{\text{all sources}} \sum_{j=1}^K E[C_D(m_j)] \int_{t_0}^{t_0 + \Delta T} \sum_{n=1}^{\infty} f_{T_{nth}}(m_j, t | T > t_0) dt$$

Earthquake probability estimation

1. Strong motion seismology
2. Geotechnical engineering
3. Structural engineering
4. Social economics, etc.



Conclusions (Case study)

Installation of oil dampers is effective in reducing expected life-cycle cost in the KKE building.



Conclusions (Case study)

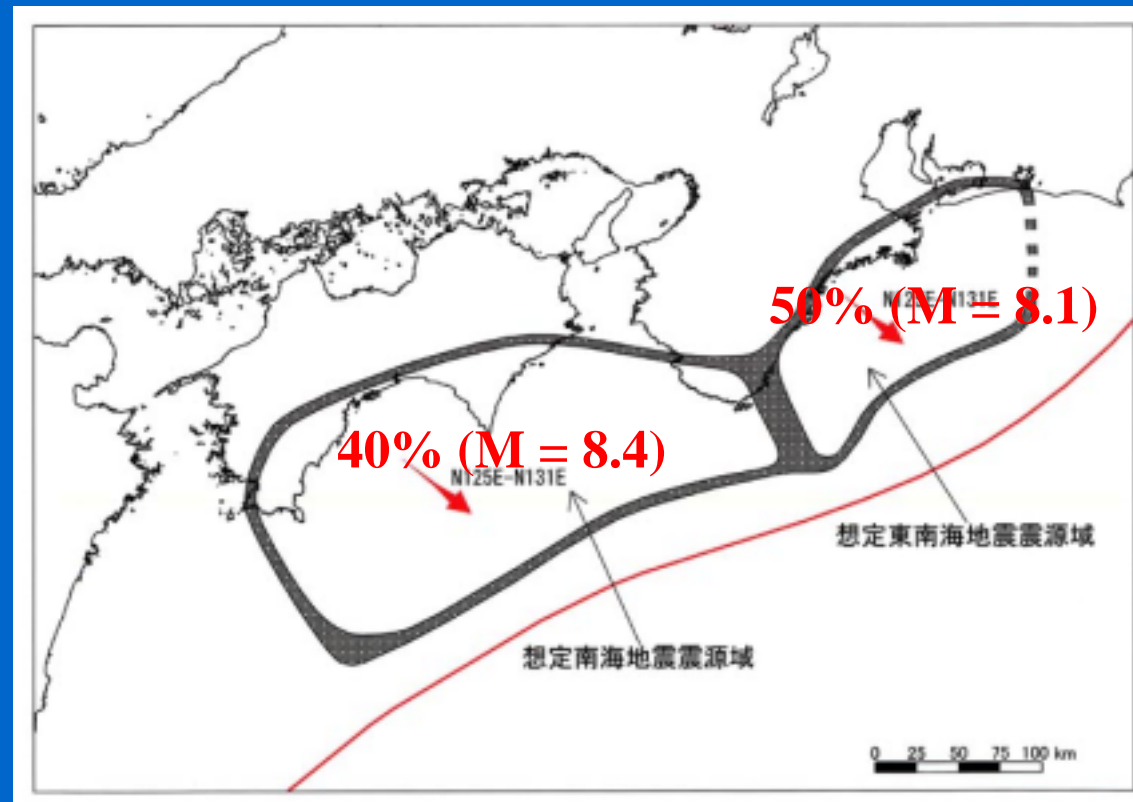
Installation of oil dampers is effective in reducing expected life-cycle cost in the KKE building.

The appropriate initial investment is cost-effective, in particular, in seismically active region.



Current study

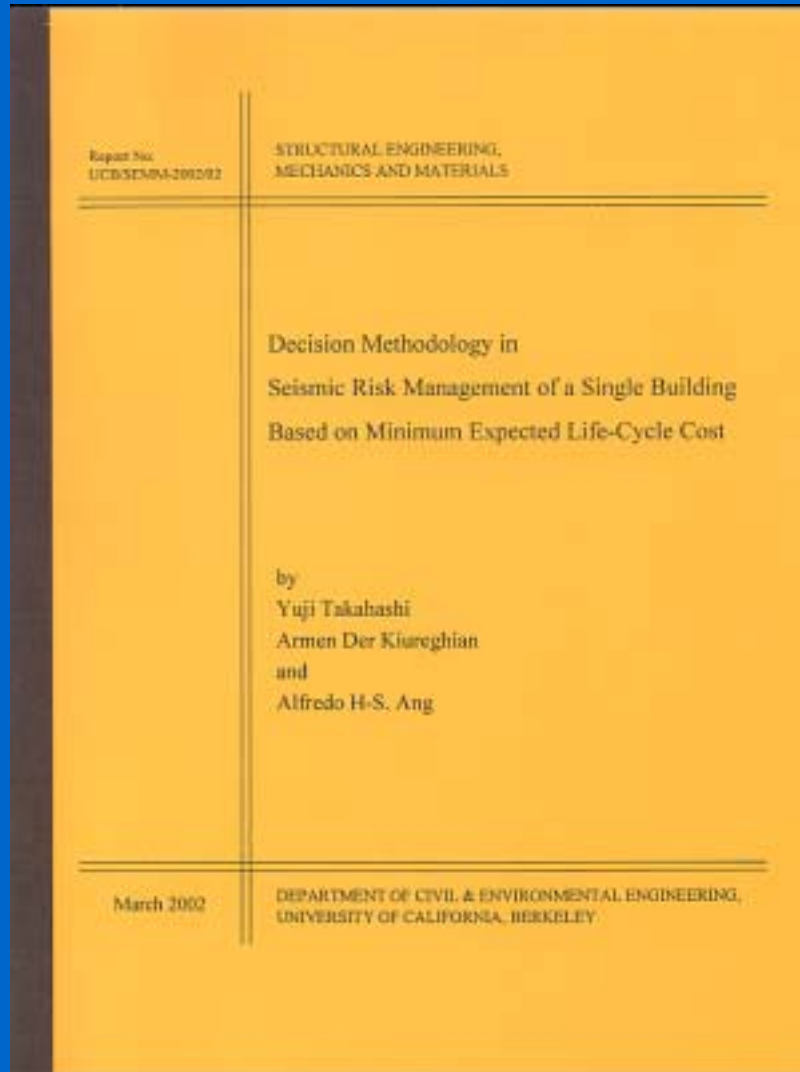
Application to seismically active regions



(HERP, 2001)



Details in UCB/SEMM Report



Yuji TAKAHASHI, Dr.Eng.

Building Research Institute

takahasi@kenken.go.jp

